Implications for the origin and evolution of Martian recurring slope lineae at Hale crater from CaSSIS observations

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#### Abstract

Recurring Slope Lineae (RSL) are narrow, dark features that typically source from rocky outcrops, incrementally lengthen down Martian steep slopes in warm seasons, fade in cold seasons and recur annually. In this study we report the first observations of RSL at Hale crater, Mars, during late southern summer by the Colour and Surface Science Imaging System (CaSSIS) on board ESA's ExoMars Trace Gas Orbiter (TGO). For the first time, we analyze images of RSL acquired during morning solar local times and compare them with High Resolution Imaging Science Experiment (HiRISE) observations taken in the afternoon. We find that RSL activity is correlated with the presence of steep slopes. Our thermal analysis establishes that local temperatures are high enough to allow either the melting of brines or deliquescence

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of salts during the observation period, but the slope and aspect distributions of RSL activity predicted by these processes are not consistent with our observations. We do not find any significant relative albedo difference between morning and afternoon RSL. Differences above 11% would have been detected by our methodology, if present. This instead suggests that RSL at Hale crater are not caused by seeping water that reaches the surface, but are best explained as dry flows of granular material.

Keywords: Recurring slope Lineae, RSL, CaSSIS, HiRISE, Mars, Relative albedo, THEMIS

## 1 1. Introduction

The origin of Recurring Slope Lineae (RSL) is one of the most controversial science questions regarding present-day surface activity on Mars. They appear as narrow (< 5 m) low-albedo streaks, often starting from bedrock outcrops and lengthening hundreds of meters down Martian steep slopes at equatorial and mid-latitudes (McEwen et al., 2011). RSL generally start lengthening during warm seasons, fade during cold ones and and recur over multiple Martian years. However, RSL activity can be more complicated than a simple repeating cycle of lengthening and fading, as several well studied sites shows simultaneous lengthening, appearance and fading of RSL (Stillman and Grimm, 2018; Vincendon et al., 2019). Many models have been proposed to explain their origin, but a definitive explanation is still elusive. These can be broadly summarized in three classes: wet models, in which RSL are water-dominated features, dry models, that explain RSL as dry mass fluxes or aeolian features, and hybrid models, in which water plays an indirect role in RSL formation and lengthening.

#### 6 1.1. Wet models

The temperature dependence of RSL activity suggests that water or brines may 17 be present (McEwen et al., 2011; McEwen et al., 2014; Stillman et al., 2014; Huber et al., 2020). Spatial correlation with multi-scale fractures appears to support 19 groundwater sources (Stillman et al., 2016; Abotalib and Heggy, 2019). However, topographic relationships cast doubts on these models, as they explain the season-21 ality of RSL activity, but require larger volumes of liquids than could be reasonably 22 present on Mars at these latitudes (Grimm et al., 2014; Chojnacki et al., 2016). 23 Moreover, many RSL source from local topographic highs, such as ridge crests or 24 peaks, where a groundwater source is unlikely (Chojnacki et al., 2016). Another wet 25 process that has been considered to explain RSL formation is the deliquescence of 26 salts, which occurs when hygroscopic salts absorb water vapor to form a liquid solu-27 tion (Gough et al., 2016). For this to happen, temperatures higher than the eutectic 28 temperature of the solution and relative humidities (RH) greater than their deliques-29 cence relative humidity (DRH) are required (Gough et al., 2016). Several laboratory 30 studies have identified chlorides (Gough et al., 2016; Wang et al., 2019), perchlorates 31 (Nuding et al., 2014) and chlorates (Toner and Catling, 2018) as potential candidate 32 deliquescent salts. The required RH values for the deliquescence of CaCl<sub>2</sub> brines range from 12.9% when T = 273 K to  $\sim 20.9\%$  at T = 233 K (Gough et al., 2016), while their eutectic temperature is T = 223K. Numerical modeling by Gough et al. (2016) showed that atmospheric water vapor could sustain the deliquescence of hydrated CaCl<sub>2</sub> brines at 3-cm depth at the Phoenix landing site. However, it is not clear whether or not the same process can happen at RSL sites (Gough et al., 2016),

even though Wang et al. (2019) recently proposed that the deliquescence of subsurface hydrated chlorides can be a thermodynamically viable (but not necessarily sufficient) process for triggering RSL activity. The deliquescence of Ca-perchlorates is also interesting because of their realtively low DRH (from  $10 \pm 4\%$  at 273 K to  $55 \pm 4\%$  at 223 K (Nuding et al., 2014)) and eutectic temperature of T = 200 K. Finally, chlorates may be even more interesting candidates as they have a lower DRH than perchlorates (Toner and Catling, 2018).

# 46 1.2. Dry models

In these models, RSL lengthening and formation are interpreted with dry mech-47 anisms involving granular flows or aeolian processes (Dundas et al., 2017; Schmidt et al., 2017; Vincendon et al., 2019; Schaefer et al., 2019). These have been initially invoked to explain the correlation between the angle of repose of granular material and the slope angle at which RSL stop (Dundas et al., 2017), although more recent measurements show that  $\sim 25\%$  of RSL reach slopes below the angle of repose 52 (Tebolt et al., 2020; Stillman et al., 2020). In addition, Schmidt et al. (2017) dis-53 cussed morphological inconsistencies between RSL and wet flows, such as the lack of 54 terminal or lateral levees; Vincendon et al. (2019) proved that RSL formation occurs 55 outside the time-frame compatible with the existence of liquid water and does not 56 show a preference for the warmest slopes. Finally, the spectral detection of hydrated 57 salts at some RSL sites (Ojha et al., 2015), which would support the presence of 58 liquids, was recently proven to not be robust (Leask et al., 2018; Vincendon et al., 2019). Although dry flows do not require a source of water, a trigger mechanism has not been fully established yet. Schmidt et al. (2017) proposed a Knudsen pump as a

trigger mechanism, but it doesn't predict RSL at the times and locations where they
are observed (Stillman and Grimm, 2018; Vincendon et al., 2019). Vincendon et al.
(2019) and Schaefer et al. (2019) proposed that RSL are aeolian features resulting
from the removal of bright dust by winds. A fading mechanism has been recently
proposed by Vincendon et al. (2019), which showed that the progressive brightening
of RSL can be attributed to dust deposition. On the other hand Schaefer et al. (2019)
discovered that the fading of RSL is similar to that of other dust-related albedo features (dust devil tracks, rockfalls) on the basis of relative albedo analyses at Tivat
crater (45° S, 9° E). They propose that RSL fade due to the widespread removal
of dust from the neighboring slopes, which progressively darken until matching the
RSL reflectance. While this mechanism applies well to Tivat crater, it cannot explain
the concurrent fading and lengthening of RSL observed in several other RSL sites
(Vincendon et al., 2019; Stillman et al., 2020).

# 75 1.3. Hybrid models

Other hypotheses envision an indirect role of water in triggering RSL activity.

Massé et al. (2016) showed that boiling fresh water can trigger granular flows by violently displacing grains. While this model is interesting because it requires less water
than wet-based models, boiling water requires high temperatures that are hardly met
at the onset of RSL activity in early spring (Stillman and Grimm, 2018; Vincendon
et al., 2019). More recently, Shoji et al. (2019) proposed that moisture serves to
stabilize steep slopes in cold seasons, which flow when drying during the warm seasons. In addition, Bishop et al. (2019) proposed that subsurface brine activity can
create surface collapse features, perhaps initiating RSL when on steep enough slopes.

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The High Resolution Imaging Science Experiment (HiRISE, McEwen et al. (2007)) 86 on board the NASA's Mars Reconnaissance Orbiter (MRO) mission is the optimal instrument to image RSL due to its high pixel scale ( $\sim 0.3$  m/pixel), which allows for digital terrain models (DTM) at  $\sim 1$  m spatial resolution. However, the Sunsynchronous orbit of MRO limits observation times between  $\sim 2$ -4 PM, during the local afternoon. The Colour and Surface Imaging System (CaSSIS, Thomas et al. (2017)), on board the ESA ExoMars Trace Gas Orbiter (TGO) mission, images the Martian surface 93 at 4.6 m/pixel in four color bands. It carries a rotation mechanism that allows it 94 to acquire stereo observations with identical illumination angles for the production 95 of DTMs. The 74° inclined orbit of TGO allows CaSSIS to observe the surface 96 at different times of day, such as the local morning. This capability is pivotal for 97 RSL studies, since morning observations of these features are not possible otherwise. The only exceptions are extremely early morning views by Mars Odyssey, with poor SNR and much lower spatial resolution. Morning activity can provide great 100 insights on the nature and formation mechanism of RSL. Laboratory studies (Gough 101 et al., 2016) and analyses of data from both the Rover Environmental Monitoring 102 Station (REMS) on board Curiosity and the Thermal and Electrical Conductivity 103 Probe (TECP) on the Phoenix lander shows that daily maximum RH values occur 104 during the early morning of local summer (Steele et al., 2017; Fischer et al., 2019), 105 suggesting that these local hours are the most favourable for deliquescence. If RSL 106 are liquid-based flows, their activity should increase in the morning, when both tem-

perature and air humidity are high enough to favor the deliquescence of salts and 108 increase the stability of brines. Under this scenario, dehydration would occur in the 109 afternoon, so we would also expect RSL to be darker in the morning than in the 110 afternoon. Instead, if RSL are caused by the melting of shallow subsurface ice (such 111 as from a deep groundwater source), then they should be darker in the afternoon. 112 This assumes that the quantity of water or brines at play is relatively small, so that 113 evaporative losses exceed the supply of water (Hillel, 2004). If instead RSL have a 114 high water content, pore water concentration would not be affected by evaporation 115 and there wouldn't be any albedo change (Pommerol et al., 2013; Levy et al., 2014). 116 The latter case, however, may not be in agreement with the very low water content 117 of RSL estimated at Garni crater (Edwards and Piqueux, 2016). Finally, if RSL are 118 dry flows, then we do not expect any albedo change between the observations. 119 In this study we present the first observations of RSL performed by CaSSIS during 120 the local morning and compare them with HiRISE observations acquired one month 121 earlier in the afternoon. In particular, we search for any differences in their over-122 all morphology (i.e. length, slope, aspect) and report relative albedo measurements 123 performed on morning and afternoon images. We analyze the thermal conditions of 124 the surface and shallow sub-surface at the time of the CaSSIS observation to assess 125 whether temperatures would either allow melting of brines or deliquescence of salts. 126

#### 7 2. Data

The study region is the central peak of Hale crater (-35.7° N, 323.5° E, see figures (2a, b)), where several areally extensive RSL have been discovered so far, making it

an ideal site to be investigated with CaSSIS. RSL in Hale were first reported by Ojha et al. (2014) and then analyzed by different authors (Stillman et al., 2014; Dundas 131 et al., 2017; Stillman and Grimm, 2018). Stillman and Grimm (2018) reported that 132 RSL activity in general may occur in one or two pulses, where RSL fade partially or 133 completely and then re-appear in the same year. The RSL at Hale crater are peculiar 134 because they seem to experience three pulses of activity (Stillman and Grimm, 2018), 135 unlike any other sites analyzed on Mars so far. Our RSL observations span an  $L_s$ 136 range between 331.5° and 347.4°, within the third pulse proposed by Stillman and 137 Grimm (2018), allowing us to confirm its presence at Hale crater. In order to study 138 whether there is a diurnal dependence in the activity of RSL, an ideal dataset would 139 include two observations of an RSL site acquired during the same Martian day, 140 the first one with CaSSIS in the morning and the second one with HiRISE in the 141 afternoon. In our case, the observations were acquired during late southern summer, 142 one month apart. The HiRISE image was acquired on  $L_s = 331.5^{\circ}$  at 14:06 local time, 143 while the CaSSIS image was acquired on  $L_s = 347.4^{\circ}$  at 11:13 local time. This time 144 interval may be too big to minimize seasonal changes between images, such as fading 145 of RSL, which typically happens during this season at southern hemisphere sites. 146 However, this issue may not be important for Hale crater, where fading was reported 147 to occur only after  $L_s > 7^{\circ}$  for both MY 30 and 31 (Stillman and Grimm, 2018), 148 well after the  $L_s$  of our observations. For this reason, we are confident that fading is 149 not influencing our analysis. Moreover, RSL at Hale crater are "rejuvenated" by a 150 third pulse of activity which occurs just before  $L_s = 331.5^{\circ}$ . The occurrence of this 151 third pulse of activity is illustrated in figure (1). HiRISE image ESP\_057\_569\_1440,

acquired at  $L_s = 286.6^{\circ}$ , shows dense RSL coverage (see fig. 1a), while the subsequent HiRISE image ESP\_058618\_1445, acquired at  $L_s = 331.5^{\circ}$ , shows smaller RSL in the 154 same places (see fig. 1b). These further lengthened in the subsequent CaSSIS image 155 MY34\_005640\_218\_2, acquired at  $L_s = 347.4^{\circ}$  (see fig. 1c). This means that the RSL 156 had completely faded and had started lengthening again between the first two images 157 (1a,b) and continued lengthening between  $L_s = 331.5^{\circ}$  and  $L_s = 347.4^{\circ}$ . This is also 158 confirmed by the analysis of HiRISE images of Hale crater in previous Martian Years 159 reported by Stillman and Grimm (2018). In particular, from figure S9 of Stillman 160 and Grimm (2018) we see that RSL lengthening occurs between 341.9°  $< L_s < 7^{\circ}$ 161 in MY 31 and 326.5°  $< L_s <$  7° MY 32. This means that despite the HiRISE and 162 CaSSIS images analyzed here being taken 30 days apart, the mechanisms responsible 163 for RSL lengthening are active during this period and any seasonal fading can be 164 considered negligible, allowing us to compare RSL albedos between the two images. 165 In the following sections we will describe our dataset, summarized in figure (2), which 166 combines HiRISE (section 2.1), CaSSIS (section 2.2) and Thermal Emission Imaging 167 System (THEMIS; Christensen et al. (2004)) (section 2.3) observations. Image IDs 168 and observation details for each of the products we used are detailed in Appendix 169 Α. 170

## 171 2.1. HiRISE data

We used the latest publicly available HiRISE image of the central peak of Hale crater, ESP\_058618\_1445, acquired on 27 January 2019 at 14:06 Mars local time and with a  $L_s=331.5^{\circ}$ , as well as the corresponding HiRISE DTM and orthophoto of the region. The RED channel (McEwen et al., 2007) of the HiRISE image was

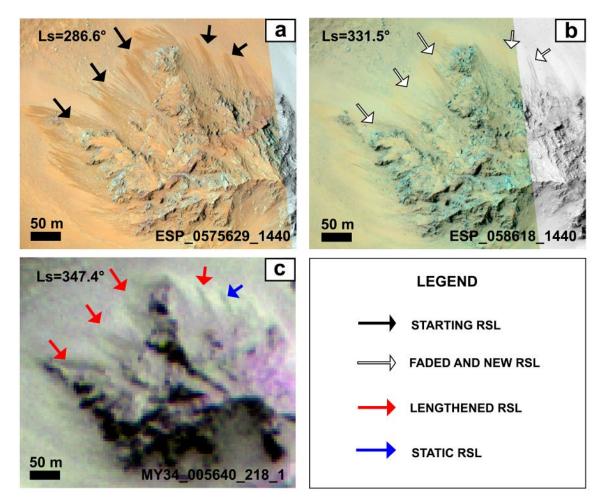


Figure 1: RSL activity during the 3rd pulse at Hale crater. a) HiRISE image showing areally extensive RSL, indicated by black arrows, at  $L_s=286.6^{\circ}$ . b) The same area but observed at  $L_s=331.5^{\circ}$ . White arrows indicate the same RSL in a) that faded and restarted their lengthening phase. c) Colour composite of the RED, PAN and BLU filters of CaSSIS image MY34\_005640\_218\_2 taken at  $L_s=347.4^{\circ}$  and showing that some a RSL in n) remained static (blue arrow) while others (red arrows) further lengthened with respect to the previous image. Areal extents of RSL in this area are mapped in figure (10).

orthorectified on the DTM using the NASA Ames Stereo Pipeline (Moratto et al., 176 2010). To obtain reliable slope and aspect measurements, we adapted the technique 177 of Schaefer et al. (2019) to reduce noise and systematic artifacts present in the DTM 178 and calculated slope and aspect maps using ArcGIS (Burrough and McDonell, 1998). 179 In particular, the DTM was resampled at 2m resolution and smoothed with a 10 m 180 radius moving average as in (Schaefer et al., 2019). The aligned HiRISE DTM, image, 181 aspect and slope maps are shown in figure (2). More details about the HiRISE data 182 products used in the analysis are provided in Appendix A. 183

## 184 2.2. CaSSIS data

The central peak of Hale crater was imaged by CaSSIS on 26 February 2019 at 185 11:13 Mars local time, with a  $L_s = 347.4^{\circ}$ , in stereo mode and with the near infrared 186 (NIR), red (RED), panchromatic (PAN) and blue (BLU) filters (Thomas et al., 187 2017). From the CaSISS stereo pair MY34\_005640\_218\_1, a DTM and radiometrically 188 calibrated orthophoto of the PAN channel of the second image in the stereo pair 189 (i.e. MY34\_005640\_218\_2) were obtained using the 3DPD photogrammetric pipeline 190 described in Simioni et al. (2017). The CaSSIS orthophoto was then manually co-191 registered to the aligned HiRISE dataset in ArcGIS. The footprint of the CaSSIS 192 stereo pair is shown in figure (2b) and a color composite image obtained by combining 193 the overlap of the RED, PAN and BLU channels is shown in figure (2c). 194

## 95 2.3. THEMIS data

We used the MARSTHERM web interface (Putzig et al., 2013) to process THEMIS infrared observations within  $\pm$  5° of L<sub>s</sub> of the CaSSIS image and derive thermal in-

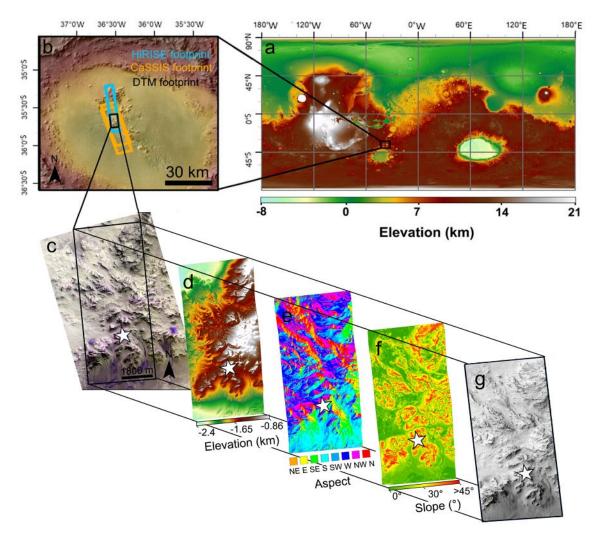


Figure 2: Schematic description of our dataset. a) Mars Orbiter Laser Altimeter (MOLA) colorized elevation map of Mars showing the location of Hale crater (black rectangle). b) MOLA colorized elevation map overlaid on THEMIS infrared daytime mosaic showing the central peak of Hale crater and the footprints of our observations. c) RGB color composite of the RED, PAN and BLU filters of CaSSIS image MY34\_005640\_218\_2 depicting the central peak of Hale crater. d) HiRISE DTM, e) aspect and f) slope maps generated from the HiRISE DTM and g) HiRISE image ESP\_058618\_1445 projected onto the HiRISE DTM. The white star indicates the location of figure (1).

ertia maps of Hale crater at 100 m resolution. As is customary for Martian thermal modeling studies (Edwards and Piqueux, 2016; Fergason et al., 2006), we considered only nighttime observations. The final thermal inertia map was obtained by computing the median thermal inertia value at each pixel from all the selected observations.

The thermal inertia map was then used to simulate surface and subsurface temperatures at Hale crater, as described in section (3.3).

## 3. Methods

## os 3.1. General properties

We first identified all RSL that were resolved in both the HiRISE and CaSSIS 206 images. Sometimes the RSL identified on the HiRISE image occurred in clusters 207 of several lineae, spanning multiple CaSSIS pixels, but separated by distances lower 208 than the CaSSIS resolution. In these cases we did not consider the single RSL, not 209 resolved by CaSSIS, but the whole cluster. We mapped the envelope of each RSL, 210 or cluster of RSL, in both images. To better compare the two images and cross-211 check any detected lengthening, we also resampled the HiRISE image at the CaSSIS 212 resolution by summing all HiRISE pixels within a CaSSIS pixel and mapped the 213 RSL envelopes on the resampled image. Examples of "changed" and "static" RSL, including their mapped envelopes are seen in figure (3). If a significant RSL lengthening could be detected using both the original and resampled images, we labeled 216 the RSL as "changed", otherwise as "static". To take into account uncertainties in 217 the comparison from any residual misalignment and/or differences in resolution and 218 illumination between the two images, we considered a lengthening to be statistically robust only if greater than 1 CaSSIS pixel. This threshold is much lower than the
typical lengthening that should occur between the two images, ~ 60-100 m given the
average RSL advance rates (Levy, 2012; Stillman et al., 2016). To distinguish darkening caused by illumination conditions (i.e. topographic shading) from real RSL in
the CaSSIS image we also considered the relative orientation between the slopes and
the direction of the Sun, and avoided comparison of albedo features within highly
shaded regions. Finally, we measured the mean slope and aspect at the termination
point of every mapped RSL in the HiRISE image.

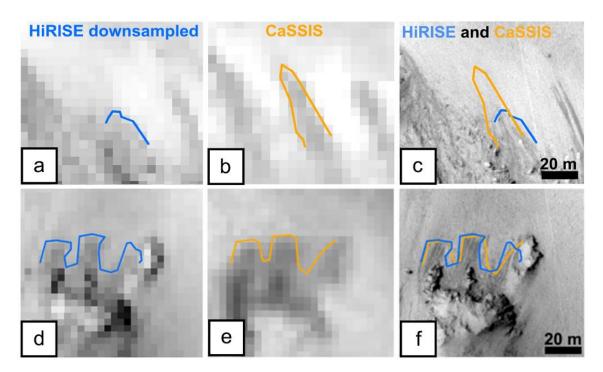


Figure 3: Examples of "changed" (upper row) and "static" (lower row) RSL envelopes mapped in blue on the downsampled afternnon HiRISE image (a,d) and in orange on the morning CaSSIS image (b,e). Panels (c) and (f) Show their comparison on top of the original HiRISE image.

#### 28 3.2. Relative albedo

The relative albedo is the ratio between the reflectance (I/F) of two atmospher-229 ically corrected regions of the surface that have the same illumination conditions (Daubar et al., 2016). Our goal is to assess if RSL are darker, and thus potentially 231 wetter, in the morning with respect to the afternoon. We compute the RSL relative albedo as the ratio between the reflectance of an RSL region and the reflectance of 233 a nearby RSL-free region with the same illumination conditions, that is assumed to 234 not have "changed". We only compare the CaSSIS PAN channel with the HiRISE 235 RED channel. As these two filters closely correspond one to each other, the consis-236 tency between HiRISE and CaSSIS measurements is granted (Thomas et al., 2017). 237 A complete multi-band analysis taking into account for differences between the CaS-238 SIS RED and NIR and the HiRISE IR filters is left for a future work. In order to 239 perform relative albedo measurements, it is necessary to first identify regions with 240 similar slope and aspect, and in turn similar incidence angles. To do this, we first 241 selected a set of regions of interest (ROI) from the previously identified RSL in both 242 images (RSL ROI). To ensure that each RSL ROI is dominated by RSL signal, we 243 used the HiRISE image for the selection and kept that same ROI in the CaSSIS 244 image. Their mean slope and aspect were measured using ArcGIS. For each RSL 245 ROI, we defined a corresponding background (BK) ROI in a nearby region, with 246 similar mean slope and aspect but without RSL in either images. Where a suitable BK ROI could not be found, we did not include the RSL in the relative albedo analysis. This criterion proved to be the most restrictive, resulting in a relatively low number of suitable ROIs for relative albedo measurement, as discussed in section

(4.2). Figure (4) shows examples of some selected ROIs. We extracted the mean I/F and its standard deviation for each BK and RSL ROI and applied a first order 252 atmospheric correction by subtracting the I/F value of the darkest pixel within shad-253 ows in the overlapping region of the two images from  $IF_{RSL}$ . To take into account 254 the different resolutions of the two images, for HiRISE we used the mean I/F in a 255  $4.6 \times 4.6$  m square area around the darkest pixel within shadows. Although this kind of atmospheric correction can be inaccurate in steep topography, it is often adopted 257 when performing relative photometry (Daubar et al., 2016; Schaefer et al., 2019). In 258 addition, more precise use of shadows areas for this purpose could be performed if 259 required (Hoekzema et al., 2011). In our case, however, we only apply the atmo-260 spheric correction to the RSL ROIs and not to the BK ones. The rationale behind 261 this approach is to take into account the non-linear effect of aerosols on the apparent 262 reflectance of a surface, meaning that low-albedo surfaces are more brightened by 263 diffuse light than high albedo ones (Vincendon et al., 2007). We finally computed 264 the relative albedo as: 265

$$RA_* = \frac{IF_{RSL} - IF_D}{IF_{BK}} \quad * \in \{H, C\}$$
 (1)

where  $RA_*$  is the RSL relative albedo, computed either from the original HiRISE (\* = H) or CaSSIS (\* = C) images.  $IF_{RSL}$  is the mean I/F extracted from an RSL ROI.  $IF_D$  is the I/F of the darkest shadowed pixel and  $IF_{BK}$  is the I/F of a BK ROI. We compute uncertainties for the HiRISE and CaSSIS relative albedos applying standard error propagation (see Appendix B). The significance of any difference between the HiRISE and CaSSIS relative albedos is established applying

standard statistical tests. We use the Kolmogorov-Smirnov (KS, Massey (1951))and Wilcoxon (W, Wilcoxon (1945)) signed-rank statistical tests to assess if the 273 HiRISE and CaSSIS relative albedos are sampled from the same distribution. We 274 apply the Anderson-Darling (AD, Anderson and Darling (1954)) and Shapiro-Wilk 275 statistical tests (SW, Shapiro and Wilk (1965)) to assess if the differences between the two distributions are stochastic. From each test, a p-value is computed and 277 compared with the customary 0.05 threshold. All tests and the p-value compu-278 tations are performed using routines implemented in the nortest library (Gross 279 and Ligges, 2015) (https://CRAN.R-project.org/package=nortest) of the R pro-280 gramming language (R Core Team, 2019). 281

## 282 3.3. Thermal analysis

We simulated diurnal surface and subsurface temperatures on the region depicted 283 in figure (5a) at the time of the CaSSIS observation using the thermal model of 284 Schorghofer et al. (2019). This model solves the 1D thermal balance and diffusion 285 equations in a rough surface, taking into account the contribution of 3D topography 286 to the surface energy balance. Examples of modeled diurnal surface and subsurface 287 temperature maps are shown in figure (6). We focused only on this region because 288 it hosts many large RSL on multiple slope orientations and allowed us to reduce 289 computation time. Within this region we defined different study zones, as depicted 290 in figure (5b). To account for the different thermal behavior of different materials 291 within our region, we distinguished between zones composed of exposed bedrock (i.e. 292 those starting with "B" in figure (5d) and zones composed of finer material, like 293 regolith (i.e. those starting with "S" in figure (5d)). For the former we estimate a

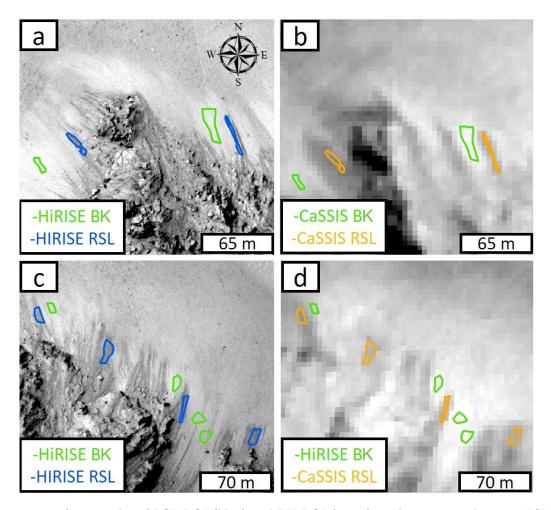


Figure 4: a,c): examples of RSL ROI (blue) and BK ROI (green) used to extract the mean I/F of RSL and RSL-free regions and their uncertainty from the HiRISE image. b,d): examples of RSL (orange) and BK (green) ROIs used to extract the mean I/F of RSL and RSL-free regions and their uncertainty from the CaSSIS orthoimage.

mean thermal inertia of  $772^{+188}_{-130}$  TIU, and for the latter we estimate a mean thermal inertia of  $540^{+128}_{-122}$  TIU (TIU is thermal inertia units, i.e. J m<sup>-2</sup> s<sup>-0.5</sup> K<sup>-1</sup>). Thermal inertia and  $3\sigma$  uncertainties were estimated by computing the mean, maximum and minimum values of pixels within the "BEDROCK" and "SLOPE" ROIs defined in

the thermal inertia map and depicted in figure (5d). These estimates are used, along 299 with a DTM of the region, to simulate the mean, maximum and minimum diurnal 300 temperature profiles at the surface and at 10 and 20 cm depth, as in (Chevrier and 301 Rivera-Valentin, 2012). Although the thermal model has already been validated by 302 Schorghofer et al. (2019) at Palikir crater, we also checked that the simulated tem-303 peratures of our zones agreed with the nighttime THEMIS IR observation I59655010, 304 acquired at a  $L_s = 348.8^{\circ}$ , close to the CaSSIS image  $L_s$ . THEMIS surface temper-305 atures were obtained using the https://www.thmproc.mars.asu.edu website and 306 are reported in figure (9).

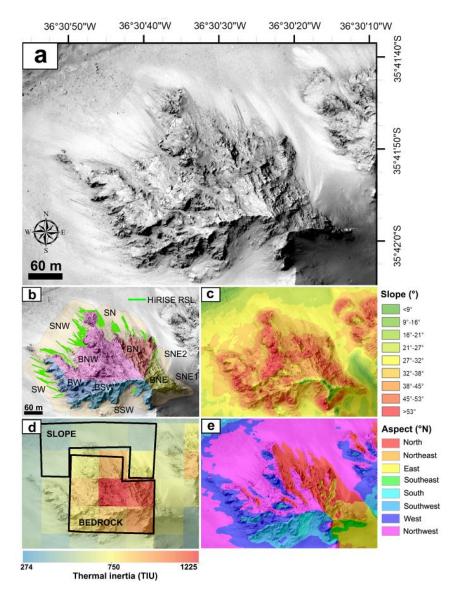


Figure 5: a) HiRISE image ESP\_058618\_1445 showing the selected region for the thermal analysis. b) Definition of zones where we simulated temperature profiles. c) Slope map. d) THEMIS-derived thermal inertia map. Black polygons represent the "BEDROCK" and "SLOPE" ROIs used to extract the thermal inertia of the bedrock material and the regolith, respectively. e) Aspect map.

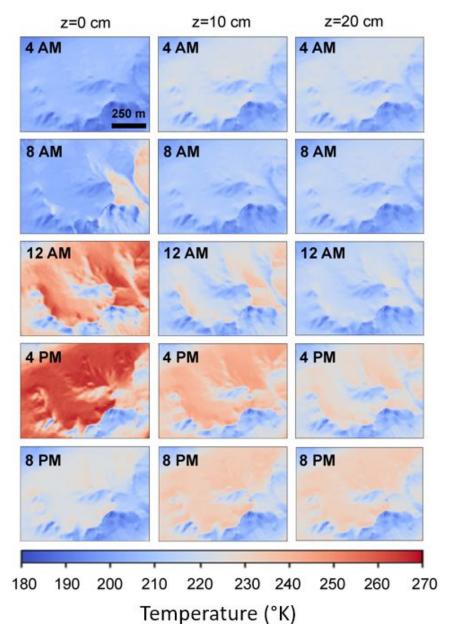


Figure 6: Example of diurnal temperature maps simulated at the surface (left), 10 cm depth (middle) and 20 cm depth (right). The simulations were performed using a THEMIS-derived thermal inertia of 770 TIU and used to extract diurnal temperature profiles for the bedrock.

#### 38 4. Results

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## 4.1. General properties

We identified 125 RSL, or groups of RSL in some cases, that were visible in 310 both the HiRISE and Cassis images. Figures (7b,c and d) show examples of RSL 311 as observed by CaSSIS. All the mapped RSL and their classification in terms of 312 significant or absent lengthening between the morning and afternoon image are shown 313 in figure (7a), while their slope and aspect distribution are in figures (8a,b). In 314 particular, the aspect distribution in figure (8b) shows that the considered RSL are 315 found on north, north-west and west facing slopes and that there is no significant 316 difference between the aspect of "static" and "changed" RSL. On the contrary, the 317 slope distribution shows a dichotomy between the two classes. Most of the "static" 318 RSL are found at slopes  $<30^{\circ}-32^{\circ}$  while most of "changed" RSL are found at 319 slopes  $> 30^{\circ} - 32^{\circ}$ . 320

## 321 4.2. Relative albedo analysis

We performed the relative albedo analysis on a selected sample of 11 RSL. The relatively low number of RSL considered for the relative albedo analysis is determined by the selection criteria discussed in section (3.2), i.e. we selected only RSL ROIs for which we could identify nearby BK ROIs having their same slope and aspect. In table (1) we report the CaSSIS ( $RA_C$ ) and HiRISE ( $RA_H$ ) RSL relative albedos, their difference and their  $1\sigma$  uncertainties. We obtain average relative albedos of  $\bar{R}A_H$  = 0.792  $\pm$  0.032 for HiRISE and  $\bar{R}A_C = 0.790 \pm 0.029$  for CaSSIS. These are broadly consistent with the relative albedo values measured by Schaefer et al. (2019) between

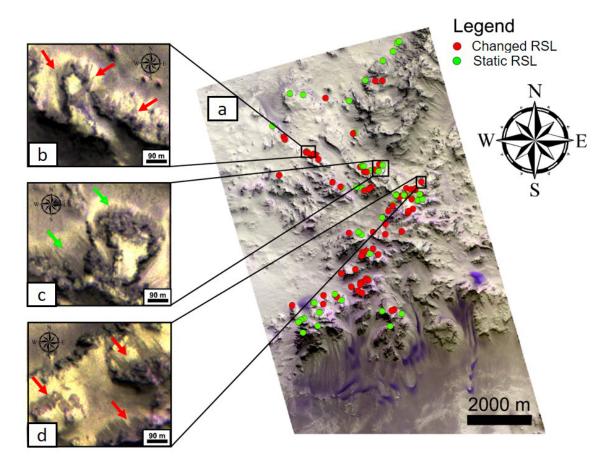


Figure 7: a) RGB color composite of the RED, PAN and BLU filters of CaSSIS image MY34\_005640\_218\_2 depicting the central peak of Hale crater. Red dots indicate "changed" RSL. Green dots indicate "static" RSL. b), c) and d): examples of identified RSL, indicated by black arrows.

 $_{330}$   $L_s = 330^{\circ}$  and  $L_s = 343^{\circ}$  at Tivat crater, prior to the fading of RSL, confirming that any possible seasonal pattern is not influencing our measurements. The RSL relative albedo values reported for each ROI in table (1) show that there are no significant differences between the HiRISE and CaSSIS observations. The uncertainty on the relative albedo differences in table (1) is given by the sum of the uncertainties on

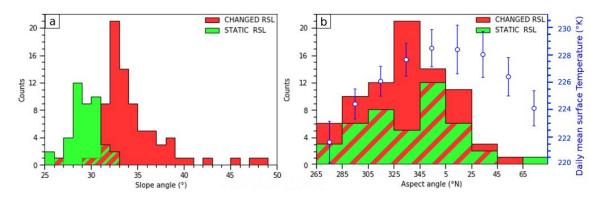


Figure 8: Distributions of a) slope and b) aspect of the termination points for "static" (green) and "changed" (red) RSL. The red-green striped part highlights where the two distributions overlap. The blue dots in b) are daily mean surface temperatures for each aspect bin for the region in figure (5). Error bars indicate the standard deviation within each aspect bin.

 $RA_C$  and  $RA_H$  and gives us an idea of the minimum albedo difference detectable by our methodology. We obtain a mean absolute uncertainty on  $RA_C - RA_H$  of 336 0.09, corresponding to an average relative uncertainty of 11%. The relative albedo 337 differences reported in table (1) are fully consistent with stochastic variability in 338 the two datasets. To demonstrate this, we checked whether the differences between 339 the HiRISE and Cassis relative albedos follow a normal distribution, applying both 340 an Anderson-Darling and a Shapiro-Wilk test of normality. We obtained p-values 341 of  $P_{AD} = 0.48$  and  $P_{SW} = 0.50$ . These are greater than the customary  $\alpha = 0.05$ 342 threshold, so we cannot reject the null hypothesis that the relative albedo differences 343 come from a normal distribution, i.e that they are stochastic. To further cross-check 344 our results, we also applied a Kolmogorov-Smirnov and a Wilcoxon signed-rank test 345 and assessed the hypothesis that the HiRISE and CaSSIS relative albedos are drawn 346 from the same distribution. Both tests failed to reject the null hypothesis, resulting 347 in p-values of  $P_{KS} = 0.99$  and  $P_W = 0.90$  both greater than the  $\alpha = 0.05$  threshold,

ROI	$RA_C$	$RA_H$	$RA_C - RA_H$
1	$0.76 \pm 0.03$	$0.79 \pm 0.06$	$-0.03 \pm 0.09$
2	$0.73 \pm 0.03$	$0.76 \pm 0.05$	$-0.03 \pm 0.08$
3	$0.79 \pm 0.02$	$0.77 \pm 0.06$	$0.02 \pm 0.09$
4	$0.80 \pm 0.02$	$0.75 \pm 0.05$	$0.05\pm0.07$
5	$0.78 \pm 0.03$	$0.75 \pm 0.05$	$0.03 \pm 0.08$
6	$0.83 \pm 0.04$	$0.80 \pm 0.06$	$0.03 \pm 0.10$
7	$0.82 \pm 0.03$	$0.85 \pm 0.06$	$-0.02 \pm 0.08$
8	$0.76 \pm 0.02$	$0.81 \pm 0.08$	$-0.05 \pm 0.10$
9	$0.83 \pm 0.04$	$0.79 \pm 0.06$	$0.04 \pm 0.10$
10	$0.79 \pm 0.02$	$0.79 \pm 0.06$	$0.00 \pm 0.08$
11	$0.81 \pm 0.03$	$0.82 \pm 0.07$	$-0.01 \pm 0.10$

Table 1: Relative albedo analysis results.  $RA_C$  and  $RA_H$  are the relative albedos of RSL with respect to nearby RSL-free slopes measured on CaSSIS and HiRISE images, respectively.  $RA_C - RA_H$  is the difference between the CaSSIS and HiRISE relative albedo. Errors are reported as  $1\sigma$  uncertainties.

confirming that the detected differences between the HiRISE and CaSSIS relative albedos are stochastic.

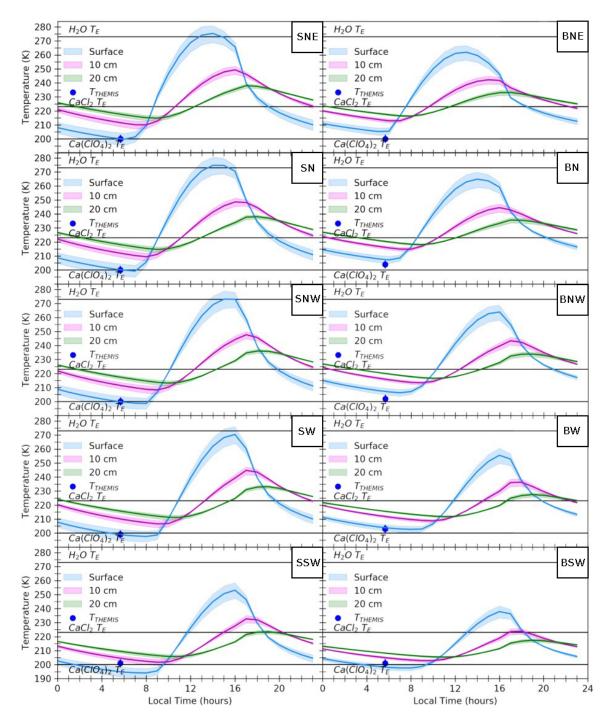


Figure 9: Diurnal temperature profiles (solid lines) with  $3\sigma$  uncertainties (shaded areas) simulated at the surface (light blue), at 10 cm (magenta) and 20 cm depth (green) for the "Slope" (left) and "Bedrock" (right) ROIs defined in figure (5). Blue dots are mean THEMIS surface temperature of each ROI with  $3\sigma$  uncertainties of 2.8 K (Fergason et al., 2006).

## 51 4.3. Thermal analysis

We simulated the thermal environment in a small region within Hale crater, 352 shown in figure (5). Diurnal surface and subsurface temperature profiles and their 353 uncertainties for each of the zones in figure (5) are shown in figure (9). In the same 354 figures, we also show the eutectic temperatures of water ice, CaCl<sub>2</sub> brine (Gough 355 et al., 2016) and Ca-perchlorate (Marion et al., 2010), as well as mean THEMIS 356 surface temperatures for each ROI. From the temperature profiles in figures (9) 357 we can see that both north-west, north and north-east regions transiently reach 358 temperatures higher than the melting temperature of water ice only at the regolith 359 surface, and not on bedrock or in the subsurface. In contrast, the transient melting 360 of  $CaCl_2$  or  $Ca(ClO_4)_2$  frozen brines is generally supported in all these zones. In 361 particular, from the temperature profiles in figure (9a) we see that north-east facing 362 slopes allow the melting of CaCl<sub>2</sub> at 10 cm in the subsurface from  $\sim 10:00$  local time 363 until  $\sim$  midnight, and at 20 cm depth from  $\sim$  12:00 to  $\sim$  14:00. On north facing 364 slopes (see figure (9b)) melting could occur from  $\sim 11:00$  to  $\sim$  midnight at 10 cm 365 depth and from  $\sim 13:00$  to  $\sim 15:00$  at 20 cm depth. On north-west facing slopes 366 (see figure (9c)) melting happens from  $\sim 12:00$  until  $\sim$  midnight at 10 cm depth and 367 from  $\sim 14:00$  to  $\sim 15:00$  at 20 cm depth. West facing slopes (see figure (9d)) allow 368 melting of from  $\sim 13:00$  until  $\sim 23:00$  local time at 10 cm depth, and from  $\sim 15:00$ 369 to  $\sim$  midnight at 20 cm depth. Finally, south-west facing slopes permit melting of 370  $CaCl_2$  mostly on the regolith and from  $\sim 15:00$  to 20:00 at 10 cm depth. At 20 cm depth, temperatures are mostly below the eutectic temperature of CaCl<sub>2</sub> brines (see figure (9e)). In all these cases, melting of  $Ca(ClO_4)_2$  is allowed at any hour of the

day at all depths, except for north-west, west and south-west facing slopes where
early morning surface temperatures are very close to 200 K and can reach values as
low as 190K, below the eutectic temperature of this brine.

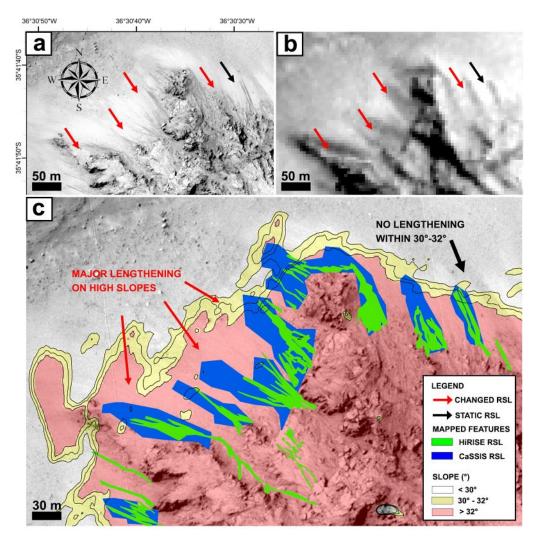


Figure 10: Mapping of HiRISE and CaSSIS RSL.a) HiRISE image depicting both "static" (black arrows) and "changed" RSL (red arrows) on the central peak of Hale crater. b) CaSSIS image showing the same RSL as in panel a). c) Mapping of HiRISE (green) and CaSSIS (blue) RSL overlain on a discretized slope map. The red part is where slopes are  $>32^{\circ}$ , the yellow part is for slopes between  $30^{\circ}$  and  $32^{\circ}$ .

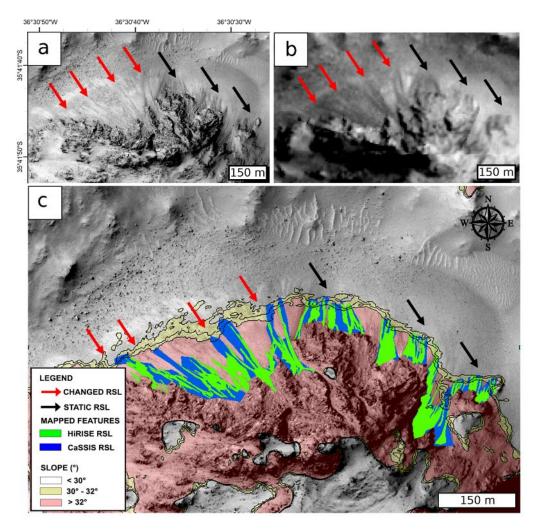


Figure 11: Mapping of HiRISE and CaSSIS RSL.a) HiRISE image depicting both "static" (black arrows) and "changed" RSL (red arrows) on the central peak of Hale crater. b) CaSSIS image showing the same RSL. c) Mapping of HiRISE (green) and CaSSIS (blue) RSL overlain on a discrete slope map. The red part is where slopes are  $> 32^{\circ}$ , the yellow part is for slopes between  $30^{\circ}$  and  $32^{\circ}$ .

# 5. Discussion

Since at Hale we observe RSL starting on bedrock outcrops (figure (10c)), which generally have lower temperatures than the freezing point of water ice but higher

than the considered brines, the latter are more likely than flows of seeping water. 380 Moreover, exposed water ice is not predicted to form on equator-facing slopes at 381 latitudes comparable to that of Hale crater (Schorghofer et al., 2019), and it is not 382 observed by spectral instruments sensitive to micrometer-thick surfaces of water frost 383 (Vincendon et al., 2010). Liquid brines may form via a) melting of a subsurface reser-384 voir or b) deliquescence of salts. In the first case, either a reservoir near the surface 385 or a subsurface deposit, which would be exposed by fractures, are necessary. The 386 fractured rocky outcrops in the central peak of Hale crater might host these shallow 387 brine reservoirs. In such a case, brine melting would occur when subsurface tem-388 peratures rise above their eutectic temperature, i.e. from mid-afternoon to evening 389 hours, depending on its depth and slope orientation. This is because ice is more 390 likely to be found in the shallow subsurface than at the surface at these latitudes. 391 In particular, our thermal analysis suggests that melting of CaCl<sub>2</sub> brines should be 392 favored on north-east, followed by north, north-west, west and south-west facing 393 slopes. Melting of  $Ca(ClO_4)_2$  brine is generally possible on all slopes, as it can oc-394 cur over most of a Martian day. However north-east, north and north-west facing 395 slopes are favored since their subsurface temperature is always higher than 200K at 396  $L_s = 347.4^{\circ}$ . This can also be explained by considering the dependence of daily mean 397 surface temperature from the slope aspect, depicted in figure (8). This predicts that 398 north-east, north and north-west facing slopes have the highest daily mean surface 399 temperatures. As a consequence, brines melting is favoured on these slopes. This 400 picture hence suggests that if RSL are formed through melting of shallow subsurface 401 brines, they should form and lengthen from noon and early-afternoon to evening hours favouring north-east, north and north-west facing slopes.

In the case of deliquescence, the main parameters constraining RSL activity are sur-404 face temperature and relative humidity. As shown in figure (9) surface temperatures 405 are above the eutectic temperature of  $CaCl_2$  from  $\sim 8:00$  to  $\sim 19:00-20:00$  Mars local time, depending on the slope orientation and thermal inertia. However, the 407 RH may not be high enough during these hours. In particular, (Steele et al., 2017) and (Fischer et al., 2019) show that from  $\sim 8:00$  to  $\sim 19:00-20:00$ , RH values are 409 below 5% both at Gale crater and at the Phoenix landing site during local summer. 410 This makes perchlorates more interesting candidates, because surface temperatures 411 are above their eutectic temperature at any time of day, except for north-west, west 412 and south-west facing and slopes during early morning. If RSL are deliquescence-413 related features, we should see a similar aspect preference as that expected for the 414 melting of brines, but more shifted towards north-east facing slopes. In fact, these 415 slopes reach higher surface temperatures at earlier local times, at a time when air 416 relative humidity is higher (Gough et al., 2016; Steele et al., 2017; Fischer et al., 417 2019), which enhances deliquescence. The aspect distribution in figure (8b) suggests 418 quite a different picture, showing a preference for north, north-west and west facing 419 slopes over north-east facing slopes. An example of this behavior is also illustrated 420 in figures (10) and (11) where RSL sourcing from north-east facing slopes are fewer 421 in number and less extensive than on north, north-west and even west facing slopes. 422 This aspect distribution may be an indication that RSL lengthening is not associated 423 with surface moisture, deliquescence of salts or melting of brines. Another option 424 may instead be that deliquescence occurs during sunset instead of early morning

when temperatures fall and relative humidity rises, as suggested by (Tebolt et al., 2020). In this case, west-facing, north-west and north facing slopes may be favoured 427 as they have slightly higher evening surface temperatures, possibly explaining the 428 aspect distribution at Hale crater. While this is in principle consistent with our as-429 pect distribution, it is not supported by either laboratory experiments (Gough et al., 430 2016), REMS (Steele et al., 2017) or TECP data (Fischer et al., 2019), which suggest, instead, that early morning hours should be more favourable for deliquescence than 432 evening hours. Moreover, it may not be in agreement with the very low water con-433 tent of RSL estimated from nighttime IR observations (Edwards and Piqueux, 2016). 434 Detailed, high-resolution modeling may be necessary to further explore the precise 435 interplay between temperature and relative humidity at RSL locations and quantify 436 the best periods for deliquescence. An indication that RSL at Hale crater may be 437 dry flows is that their lengthening stops at slope angles  $\sim 30^{\circ}$  (Dundas et al., 2017). 438 We also detect this behavior in our slope distribution in figure (8a) and in figures 439 (10,11), which show that RSL lengthening is generally correlated with the presence 440 of slopes steeper than  $\sim 30^{\circ} - 32^{\circ}$ . On the contrary, RSL that already reached slopes 441 within this range or shallower remained static. This dichotomy is shown in figure 442 (8a), where there is a significant difference between the "changed" and "static" slope 443 distributions. This dichotomy is expected for dry flows that stop when they reach 444 the angle of repose, producing the observed sample of "static" RSL, and lengthen 445 on steeper slopes, producing the observed sample of "changed" RSL. In one case, we 446 also detect a RSL that lengthened at a slope angle of  $\sim 26^{\circ}$ . A similar behaviour has 447 also been detected by Stillman et al. (2020) and Tebolt et al. (2020). Although, in

principle, this would support wet-based flows, the fact that they occur with a very low frequency suggests that these RSL could be statistical outliers (Stillman et al., 450 2020). As such, it is possible that additional and/or different mechanisms may be at 451 play in this sample of RSL. Dedicated analyses considering statistically significant 452 occurrences of these RSL and consideration of uncertainties in the DTM used for 453 computing the slope values may be necessary to reach a definitive conclusion. Our comparison of HiRISE and CaSSIS RSL relative albedo indicates that there are no 455 significant diurnal variations between 11:13 and 14:06 local time, a result expected 456 for dry flows. However, it may be also possible that significant dehydration has 457 already occurred at 11:13, producing the observed result independently from how 458 RSL form, or that the relative albedo differences at play are lower than 11%. If 459 RSL are formed through deliquescence, the importance of this issue depends on salt 460 composition and its interaction with the regolith, as these both affect the DRH and 461 ERH (efflorescence relative humidity) of the solution (Nuding et al., 2014). In par-462 ticular, Nuding et al. (2014) showed that liquid  $Ca(ClO_4)_2$  brines persist with very 463 low RH values. Therefore, if liquid brines form on early morning they may persist 464 until late morning in a metastable state and dehydrate during the afternoon. Again, 465 detailed near-surface relative humidity modeling should be performed to determine 466 whether these processes are occurring at RSL sites. Another interpretation of our 467 relative albedo measurement, which is not supported by thermal studies (Edwards 468 and Piqueux, 2016), is that the water supply exceeds evaporative losses. In this case 469 dehydration does not occur and there is no significant albedo variation (Hillel, 2004). 470 Future observations acquired during early morning will help to better characterize

the diurnal albedo of RSL. Nevertheless, the relative albedo measurements reported here could provide a useful validation for modeling and experimental studies of RSL. 473 In summary, our result collectively support dry flows as responsible for RSL 474 lengthening. The triggering mechanisms which initiate these flows may involve thermal creep (Schmidt et al., 2017; Schaefer et al., 2019), or aeolian processes (Vin-476 cendon et al., 2019). In particular, the latter would also be able to describe the temporal evolution of RSL activity during the third pulse shown in figure (1) (Vin-478 cendon et al., 2019). While our results support dry flows models, brines and more 479 generally volatiles may still play and indirect and concurrent role in RSL formation 480 by triggering dry mass fluxes (Massé et al., 2016; Wang et al., 2019; Bishop et al., 481 2019), but our data does not provide any additional insight on RSL triggering. 482

## 6. Summary and Conclusions

We presented the first CaSSIS observation of RSL obtained during local morning 484 at Hale crater, Mars. We identified a set of 125 RSL and studied their overall 485 morphology, slope and aspect distributions and analyzed their thermal environment. 486 We performed an initial comparison of their relative albedo using morning CaSSIS 487 and afternoon HiRISE observations. Our comparison of RSL, as viewed through 488 HiRISE and CaSSIS, 30 days later, reveals that most RSL lengthening occurred 489 where slopes  $> 30^{\circ} - 32^{\circ}$  were available. Instead, RSL on slopes  $> 30^{\circ} - 32^{\circ}$  remained generally static. This result supports a dry granular flow dynamics, as suggested by 491 other authors (Dundas et al., 2017; Vincendon et al., 2019; Schaefer et al., 2019; McEwen et al., 2019). The simulated diurnal surface and subsurface temperature

profiles at Hale crater suggest that melting of brines and deliquescence of salts would be both favoured on north-east facing slopes, followed by north and north-west facing 495 slopes. However, this pattern is different from our observed aspect distribution of 496 "changed" RSL at Hale crater, suggesting that RSL lengthening is not controlled by 497 surface moisture, deliquescence of salts or melting of brines. We compared HiRISE 498 and CaSSIS RSL relative albedo between 11:13 and 14:06 local time, respectively, and found no significant differences, another result expected for dry flows. Our 500 measurements could provide a useful validation for future models and experimental 501 studies on RSL formation and lengthening. We conclude that the RSL at Hale 502 crater are best explained as dry flows, in agreement with the conclusions of other 503 authors (Dundas et al., 2017; Vincendon et al., 2019; Schaefer et al., 2019; McEwen 504 et al., 2019). These may be triggered through thermal creep (Schmidt et al., 2017; 505 Schaefer et al., 2019), aeolian processes (Vincendon et al., 2019), or very limited brine 506 activity (Massé et al., 2016; Wang et al., 2019; Bishop et al., 2019). Future CaSSIS 507 observations of RSL sites acquired earlier in the morning, in combination with same-508 day afternoon HiRISE images, will be pivotal in improving the characterization of 509 the diurnal activity of RSL and will provide a clearer picture of their formation 510 mechanism. 511

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# Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper

## 531 Appendix

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In Appendix A we report some details of the products used for the analysis, such as image IDs, resolution, solar longitude, local solar time, incidence, emission and phase angles. In Appendix B we show details on the error propagation for computation of relative albedo uncertainties.

## 536 Appendix A. Dataset details

We report in table (A.2) some details on the data products defined in section (2) of the main text.

Product type	ID	Resolution	$L_s$	LTST	Incidence	e Emission	n Phase
		$\mathbf{m}$	(°)	hh:mm	(°)	(°)	(°)
HiRISE orthoimage	ESP_031203_1440_RED_C_01_ORTHO	0.25	287.7	14:40	$37.0^{\dagger}$	$13.9^{\dagger}$	$23.5^{\dagger}$
HiRISE Image	ESP_058618_1445_RED	0.50	331.5	14:06	37.0	4.0	40.7
HiRISE DTM	DTEEC_030715_1440_030570_1440_A01	1.00					
CaSSIS stereo image 1	MY34_005640_218_1	4.65	347.4	11:13	32.8	11.4	23.4
CaSSIS stereo image 2	2 MY34_005640_218_2	4.65	347.4	11:13	32.8	10.6	40.1
THEMIS IR image	I01144003	100.00	344.1	03:18	119.1	0.7	118.7
THEMIS IR image	159655010	100.00	348.4	05:40	84.6	1.9	84.4
THEMIS IR image	I67826009	100.00	341.1	06:30	91.2	0.7	91.1

Table A.2: Summary of the products used in the analysis. Solar longitude  $(L_s)$ , Local time (LTST), incidence, emission and phase angles are taken from https://www.uahirise.org for HiRISE, and from http://viewer.mars.asu.edu/ for THEMIS. †The reported incidence, emission and phase angle refers to the corresponding HiRISE Reduced Data Record (RDR) product.

## 539 Appendix B. Relative albedo uncertainty

We defined the relative albedo (see text for details) as:

$$RA_* = \frac{IF_{RSL} - IF_D}{IF_{BK} - IF_D} \qquad * = H, C \tag{B.1}$$

where  $RA_*$  is the RSL relative albedo and \* is H for HiRISE and C for CaSSIS.  $IF_{RSL}$  is the mean I/F extracted from an RSL ROI.  $IF_D$  is the I/F of the darkest shadowed pixel and  $IF_{BK}$  is the I/F of a BK ROI. To compute the uncertainties in our relative albedo measurements, we used a standard error propagation approach. In particular, we performed the following approximation:

$$\sigma_{IF_{RSL}-IF_D} \sim 2 \cdot \sigma_{IF_{RSL}}$$
 (B.2)

$$\sigma_{IF_{BK}-IF_{D}} \sim 2 \cdot \sigma_{IF_{BK}}$$
 (B.3)

where  $\sigma_{IF_{RSL}-IF_D}$  and  $\sigma_{IF_{RSL}-IF_D}$  are the uncertainties of the numerator and denominator of equation (B.1). This approximation is justified for two reasons: first, we do not have an unambiguous way to define a ROI within shadows in and retrieve its mean flux and its standard deviation. Second, we do not know the errors on the HiRISE or CaSSIS radiometric calibration equations and thus we cannot propagate the uncertainty on the Digital Number (DN) of the darkest shadowed pixel. Instead, we can reasonably expect its uncertainty to be of the same order of magnitude as the uncertainty in  $IF_{RSL}$  and  $IF_{BK}$ . With this approximation, the uncertainty on relative albedo measurements may be propagated as:

$$\sigma_{A_*} = \sqrt{\left(\frac{\partial A_*}{\partial (IF_{RSL} - IF_D)}\sigma_{IF_{RSL} - IF_D}\right)^2 + \left(\frac{\partial A_*}{\partial (IF_{BK} - IF_D)}\sigma_{IF_{BK} - IF_D}\right)^2} = \frac{1}{2}$$

$$=A_*\sqrt{\left(\frac{2\sigma_{IF_{RSL}}}{IF_{RSL}-IF_D}\right)^2+\left(\frac{2\sigma_{IF_{BK}}}{IF_{BK}-IF_D}\right)^2}$$

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