

## Geokinematics of Central Europe: New insights from the CERGOP-2/Environment Project

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### Abstract

The Central European Geodynamics Project CERGOP-2, funded by the European Union from 2003 to 2006 under the 5th Framework Programme, benefited from repeated measurements of the coordinates of epoch and permanent GPS stations of the Central European GPS Reference Network (CEGRN), starting in 1994. Here we report on the results of the systematic processing of available data up to 2005. The analysis has yielded velocities for some 60 sites, covering a variety of Central European tectonic provinces, from the Adria Indenter to the Tauern Window, the Dinarides, the Pannonian Basin, the Vrancea Seismic Zone and the Carpathian Mountains. The estimated velocities define kinematical patterns which outline, with varying spatial resolution depending on the station density and history, the present-day surface kinematics in Central Europe. Horizontal velocities are analyzed after removal from the ITRF2000 estimated velocities of a rigid rotation accounting for the mean motion of Europe: a  $\sim 2.3$  mm/year north–south oriented convergence rate between Adria and the Southern Alps that can be considered to be the present-day velocity of the Adria Indenter relative to the European Foreland. An eastward extrusion zone initiates at the Tauern Window. The lateral eastward flow towards the Pannonian Basin exhibits a gentle gradient from 1 to 1.5 mm/year immediately east of the Tauern Window to zero in the Pannonian Basin. This kinematic continuity implies that the Pannonian plate fragment recently suggested by seismic data does not require a specific Eulerian pole. On the southeastern boundary of the Adria microplate, we report a velocity drop from 4 to 4.5 mm/year motion near Matera to  $\sim 1$  mm/year north of the Dinarides, in the southwestern part of the Pannonian Basin. A positive velocity gradient as one moves south from West Ukraine across Rumania and Bulgaria is estimated to be 2 mm/year on a scale of 600–800 km, as if the crust were dragged by the counterclockwise rotation along

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the North Anatolian Fault Zone. This regime apparently does not interfere with the Vrancea Seismic Zone: earthquakes there are sufficiently deep (>100 km) that the brittle deformation at depth can be considered as decoupled from the creep at the surface. We conclude that models of the Quaternary tectonics of Central and Eastern Europe should not neglect the long wavelength, nearly aseismic deformation affecting the upper crust in the Romanian and Bulgarian regions.

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## 1. Introduction

The easternmost seismogenic area of Europe is connected to the Carpathians, the mountain belt which extends east from the Alps into Central Europe. The Carpathians were formed in the Miocene as a result of collision between the Eurasian plate and several microplates. Back arc and intra arc extensional basins, which accompanied the collision, are the Pannonian Basin, separating the Carpathians from the Dinarides, and the Transylvanian Basin. Horváth and Royden (1981) pointed out the occurrence of thinning and updoming of the lithospheric mantle, thermal contraction and related subsidence in a post-rift phase of basin formation. In general, uplift, denudation and sedimentation are competing processes in the Transdanubian zone and all need to be considered to understand the neotectonic pattern of this part of Central Europe (Fodor et al., 2005). Convergence with the Nubia plate is mirrored by seismic activity at considerable depth (>100 km) in the Vrancea Seismic Zone, and to some extent by the kinematics of the Adria microplate and the Pannonian Basin. Based on the GPS velocities computed by Grenerczy et al. (2000, 2005) and Grenerczy and Kenyeres (2006), Fodor et al. (2005) identified three kinematic units in Central Eastern Europe: a western unit, located east of the Southern Eastern Alps and responding to the updoming in the Tauern Window by lateral escape; a northeastern unit, interacting directly with the northeastern Carpathians, which accommodate the eastward motions; and a southeastern unit interacting with the Southern Carpathians, which contains the Vrancea Seismic Zone. All these three units are characterized by an eastward motion accommodated by sinistral faults to the north and dextral faults to the south. Very little is known on the kinematics and the deformation east and southeast of the Carpathians, where the European platform is generally assumed to be substantially stable. This assumption is certainly consistent with the lack of brittle deformation implied by the low to absent surface seismicity in this area. However, coupling with the counter clockwise rotation of the Anatolian block in the South is not unlikely and it cannot be excluded a priori that the European platform south of the Carpathians is itself undergoing active stretching.

In this paper we intend to make a more detailed analysis of the present-day kinematics of the Alpine–Carpathian–Pannonian–Dinaric region. As part of the activities of the Central European GPS Geodynamic Reference Network (CEGRN) (Barlik et al., 1994; Fejes, 2006), GPS campaigns were carried out from 1994 to 2006 involving both permanent and epoch stations across Central Europe. Systematic reprocessing of the campaigns, and additional campaigns done under the EU sponsored Projects CERGOP and CERGOP-2, have enabled us to extend the work of Grenerczy and Kenyeres (2006) and detail the

horizontal velocities of sites, their uncertainty, and the velocity field associated with the horizontal motion. The potential of GPS data for a better understanding of the 4-D topographic evolution of the orogens and intraplate regions of Europe has recently been reviewed by Cloetingh et al. (2007) in the frame of the TOPO EUROPE Project. The average velocity field resulting from the interpolation of a dense network of GPS stations can provide a unique link among several processes controlling the evolution of Central Europe. In this sense the CEGRN network, covering several European Nations for more than 10 years and with increasing spatial resolution, has a greater potential than previous research based on more localized networks.

## 2. Tectonic structure

### 2.1. Kinematics

The tectonic history of the Carpathian–Pannonian system is dominated by plate interactions to its south (Fig. 1). The break up of Pangea in the early Mesozoic created the Tethys Ocean and an irregular continental margin across what was then Southern Europe. This rifting also produced a collage of microplates between the major paleo-Eurasian and paleo-Afro-Arabian plates. The tectonic development of the region generally reflects the relative movements between the large plates, and the complications posed by the intervening microplates produced the puzzling geology in the Mediterranean region (Anderson and Jackson, 1987). The tectonic evolution of the Carpathian Mountains—Pannonian Basin system continues to the present. Active seismicity is concentrated at depths of up ~200 km in the Vrancea region north of Bucharest (Stephenson et al., 1996).

During the Cenozoic, the Carpathian Arc evolved to assume its strongly arcuate shape (Csontos, 1995). This block underwent both rotations and translations. The subduction of oceanic areas between this block and paleo-Europe produced considerable Neogene volcanism (Seghedi et al., 2004). The resulting arc-related terranes were accreted to Paleozoic terranes to the north and east, resulting in the formation of the Carpathian fold and thrust belts. Back arc extension played a major role in the formation of the Pannonian Basin. Lithospheric anisotropy inherited from the time of subduction can concentrate strain and induce large-scale deformation far away from the active plate margins (Matenco et al., 2007). During Miocene times, subduction and volcanism were gradually extinguished along the Carpathian arc from west to east and then to the south. The migration of the young Carpathian orogenic belt was limited by the edge of the European Platform. A slab can now only be detected at the southeastern bend of the Carpathian arc, at the Vrancea zone (Oncescu, 1984), where present-day deformation

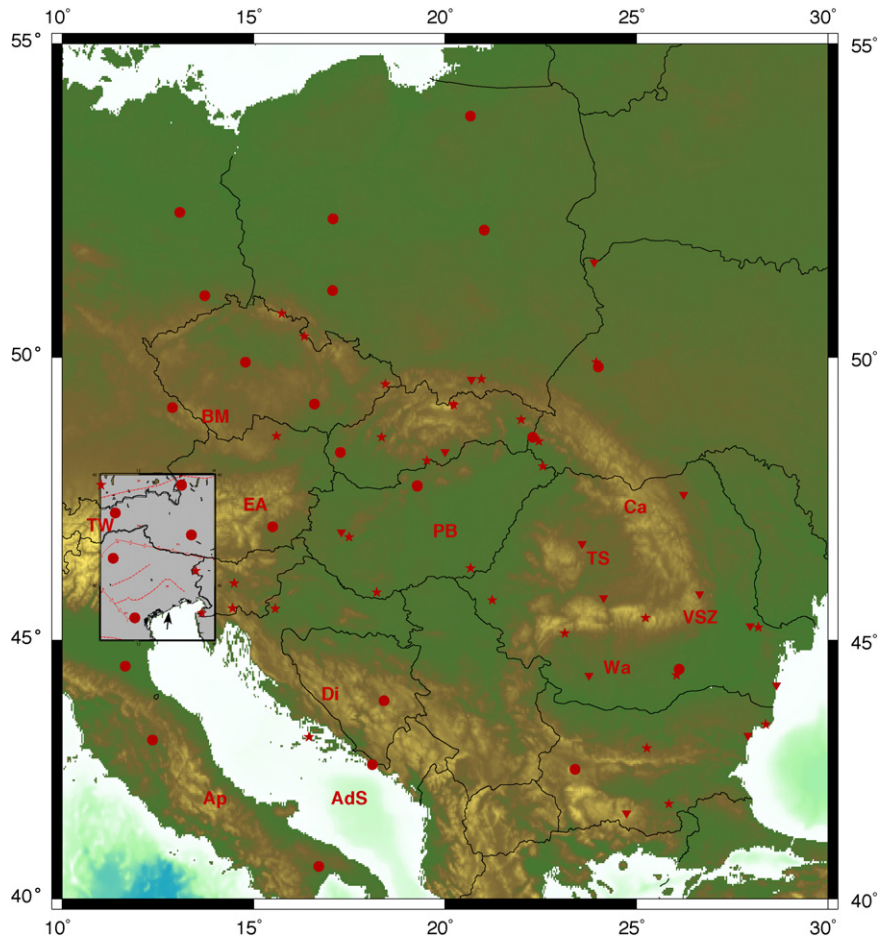


Fig. 1. Major morphological units of Continental Europe, the Mediterranean and the Hellenic arc. TW = Tauern Window; EA = Eastern Alps, BM = Bohemian Massif, PB = Pannonian Basin, Di = Dinarids, Ap = Apennines, AdS = Adriatic Sea, Ca = Carpathians, VSZ = Vrancea Seismic Zone, Wa = Wallachia, TS = Transylvania. Superimposed are the stations of the CEGRN network. Red circles indicate permanent stations which are part also of the European Permanent Network EPN; red inverted triangles indicate permanent CEGRN Stations; red stars indicate campaign (epoch) CEGRN stations. In the insert: EF = European Foreland, AI = Adria Indenter, PL = Periadriatic Lineament, SV = Schio Vicenza line. The black arrow indicates the direction of indentation of the Adriatic wedge. The indentation is accommodated by the sinistral strike slip on the West, called the Schio Vicenza line, which however shows no historical seismicity.

is being investigated by dense local GPS surveys (Dinter et al., 2001; van der Hoeven et al., 2003).

## 2.2. Crust

The Adriatic Indenter, the Eastern Alps, the European Foreland and the Pannonian Basin differ significantly in their crustal structure. The crustal and lithospheric thickness of the Central European Foreland ranges between 40–50 km and 180–200 km respectively (Majdański et al., 2007). Thickening of the crust is observed in the region of the Tauern Window and Friuli, North East Italy, consistently with the isostatic compensation of the topography. Beneath that domain the lithosphere forms a root reaching a depth of 220 km (Scarascia and Cassinis, 1997). In contrast, the crust and lithosphere of the Pannonian Basin is thin and warm. Through intense Oligocene–Miocene stretching, the crust was thinned to 22–30 km (Horváth, 1993). High heat flow causes a weak crust and is responsible for a loss of lithospheric strength. The heat flow pattern changed significantly from the Oligocene to the present. In Miocene times extensional tectonics accompanied by the exhumation of large hot core complexes

(e.g. Tauern Window; Ratschbacher et al., 1991; Neubauer et al., 2000) and magmatic activity, especially within the Pannonian Basin and along the Periadriatic Lineament, caused elevated surface heat flows. The average present-day heat flow of the European Platform is around  $60 \text{ mW m}^{-2}$ . In contrast, an average heat flow of  $90 \text{ mW m}^{-2}$  makes the Pannonian crust and lithosphere weak in comparison to the cold and thick equivalents of the European Platform (Lenkey, 1999). These thermal properties of the crust affect the strength envelope and are an important factor in the analysis of the deformation implied by the GPS velocities.

## 2.3. Stress

The counter clockwise rotation of the Adriatic microplate around a pole at  $46.1^\circ\text{N } 6.9^\circ\text{E}$  with an angular velocity of  $0.35^\circ/\text{Myr}$  (Caporali and Martin, 2000; Grenerczy et al., 2005) represents a major source for tectonic stress within the Alpine–Pannonian region. The stress regime changed from the Eocene to the present. Several stages of deformation patterns have been worked out for the northern Eastern Alps (Peresson

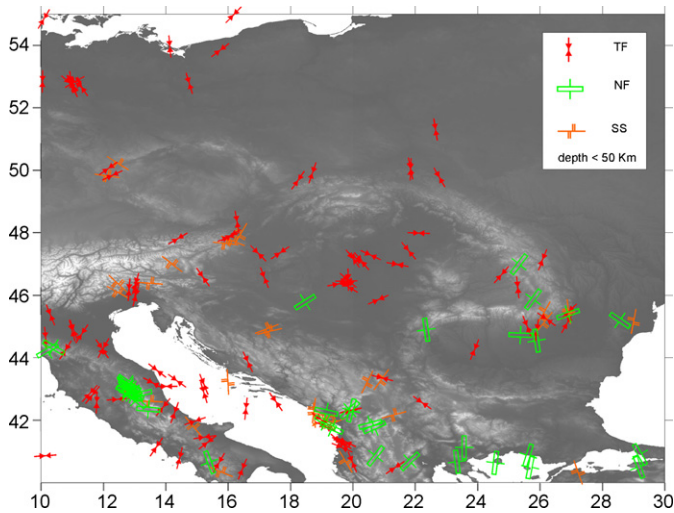


Fig. 2. Stress in Europe from a combination of geophysical data under the International Lithospheric Project (Reinecker et al., 2005). Data referring to depth <50 km and quality better than D are plotted. Regimes: TF=thrust fault; NF=normal fault; SS=strike slip. Digital Earth Model: GTOPO30 of the National Oceanic and Atmospheric Administration. Decimation: 1/5.

and Decker, 1997), for the Southern Alps (Castellarin et al., 2000; Fellin et al., 2002), the Vienna and Danube basins (Fodor, 1995), and the Pannonian Basin and western Carpathians. The paleostress patterns from the domain of the Eastern Alps and the Pannonian Basin are similar, while the Southern Alps show significant differences.

The maximum horizontal stress ( $S_H$ ) orientation of the Central European stress province rotates gradually and remains radial relative to the Carpathian arc (Fig. 2) (Reinecker and Lenhard, 1999). The Bohemian Massif shows a Central European stress pattern. This rigid block is flanked by units in the south and the east with a lower rheological strength. This rheology contrast is reflected by the radial stress pattern around the Southern Bohemian Massif (Reinecker and Lenhard, 1999; Bada et al., 1998). The stress trajectories are perpendicular to boundaries of high rheological contrast. The  $S_H$  of the Bohemian Basin and the Dinarides is NE oriented and therefore normal to the orogen (Gruenthal and Stromeyer, 1992). The stress pattern can be traced into the Pannonian Basin (Horváth and Cloetingh, 1996). Within the basin the stress trajectories diverge. The western part of the Pannonian Basin belongs to the Central European stress province. The orientation of  $S_H$  in the eastern part of the

Pannonian Basin is NNE to NE while the central Pannonian Basin shows a  $S_H$  orientation of WNW to NW.

The Eastern part of the Pannonian Basin represents a transition zone between the Western European stress province and the Dinarides stress province, the latter displaying predominantly E–W compression. The Adriatic stress province is characterized by north–south compression. As shown in the portion of Fig. 2 referring to the middle–lower Adriatic Sea,  $S_H$  progressively changes from NNE–SSW to ENE–WSW. These changes reflect the transition to the Pannonian–Dinaric stress province (Reinecker and Lenhard, 1999; Bada et al., 2007).

### 3. The CERGOP velocities and velocity field in Central Europe

The locations of epoch and permanent GPS long-term observations of sites in Central Europe, the Eastern Alps, Dinarides and Balkans forming the CEGRN network are shown in Fig. 1. The permanent GPS stations in the region were used to ensure that the resulting realization of the Terrestrial Reference System is as rigorously as possible aligned and scaled to the state of the art International Terrestrial Reference Frame ITRF2000 (Stangl, 2002; Becker et al., 2006; Hefty, 2006). Network coordinates and their covariance matrices from all eight CEGRN epoch campaigns solutions are used here as input for estimating the velocity field. The epoch-wise observing campaigns of CEGRN, comprising five 24-hour simultaneous sessions, have been performed since 1994. Initially, they were realised annually, in 1994, 1995, 1996, 1997, and then bi-annually in the late spring in 1999, 2001, 2003 and 2005.

The processing strategy was identical for all 8-epoch campaigns. Campaigns from 1994 to 2001 were reprocessed in 2002 with improved models (Becker et al., 2002a,b). The main features of the computation strategy were: processing in daily intervals (0–24 h UT), celestial reference frame realised by IGS orbits and corresponding Earth Rotation Parameters (ERPs),  $10^\circ$  elevation cut-off, station zenith delays estimated at hourly intervals, Niell (1996) mapping function, and elevation dependent weighting. Models of relative phase centre variations were consistent with IGS values. The number of observed stations included in CEGRN was gradually increased. The first epoch campaign in 1994 included 23 stations. In 1995 the network comprised 32 CEGRN stations (9 of them observed already permanently at that time) and included a further 4 IGS reference

Table 1  
Main features of CEGRN campaigns analyzed in this paper

Observing campaign	Epoch of observation	No. of processed sites in the final solution	No. of solutions forming the network combination	RMS of unit weight for the combined solution (m)
CEGRN'94	1994.34	27	3	0.0023
CEGRN'95	1995.41	36	3	0.0029
CEGRN'96	1996.45	37	3	0.0030
CEGRN'97	1997.43	45	4	0.0026
CEGRN'99	1999.46	61	3	0.0024
CEGRN'01	2001.47	55	2	0.0027
CEGRN'03	2003.46	72	4	0.0024
CEGRN'05	2005.47	95	5	0.0016



Table 2  
 Velocities of CEGRN sites observed three or more epochs expressed in geocentric coordinate system, number of campaigns, time span covered by epoch campaigns

Site	No of campaigns	Time span (years)	$v_x$	$\sigma_{v_x}$	$v_y$	$\sigma_{v_y}$	$v_z$	$\sigma_{v_z}$
BASO	4	3	-18.0	4.6	14.3	1.5	11.2	4.7
BOR1	8	11	-17.2	0.4	16.1	0.2	7.2	0.6
BOZI	4	6	-18.8	3.3	16.1	1.0	10.3	3.5
BRSK	8	11	-18.9	1.1	19.4	0.4	8.9	1.2
BUCA	6	10	-13.5	2.3	20.0	1.1	10.2	2.5
BUCU	4	6	-18.2	2.9	16.6	1.5	5.4	3.1
BZRG	4	6	-15.7	3.5	16.9	1.0	7.9	3.7
CSAN	4	6	-18.0	3.5	17.2	1.6	8.1	3.8
CSAR	8	11	-18.2	1.2	17.1	0.5	8.5	1.3
DISZ	8	11	-18.4	1.1	19.5	0.4	6.5	1.3
DRES	4	6	-12.0	2.3	17.3	0.8	15.5	2.8
DUBR	3	4	-22.1	5.8	14.7	2.3	7.3	5.6
FUN3	4	6	-6.8	3.6	21.4	1.8	14.1	4.0
GILA	4	4	-31.2	4.5	11.0	2.0	-8.5	5.1
GOPE	8	11	-16.2	0.9	17.5	0.3	8.5	1.1
GRAZ	8	11	-17.6	0.3	18.0	0.1	8.1	0.4
GRMS	4	4	-15.7	8.1	21.8	2.4	11.6	8.9
GRYB	8	11	-18.4	1.1	16.0	0.4	7.2	1.3
HARM	4	9	-18.2	1.9	18.0	0.9	5.3	2.0
HFLK	6	10	-14.0	1.7	18.1	0.5	10.5	1.8
HOHE	7	11	-13.9	1.1	16.7	0.3	12.9	1.2
HUTB	8	11	-17.9	2.0	18.2	0.7	8.4	2.4
HVAR	5	8	-24.6	1.8	18.8	0.6	7.1	1.7
IAS3	3	4	-28.8	4.0	11.7	2.1	0.5	4.8
JOZE	8	11	-17.8	1.0	16.2	0.4	7.7	1.4
KAME	4	6	-18.6	3.1	16.4	1.3	6.8	3.7
KIRS	5	5	-17.3	3.0	16.6	1.0	8.0	3.8
KOSG	8	11	-13.5	0.3	16.6	0.1	9.7	0.5
LAMA	8	11	-18.8	1.0	13.8	0.4	4.7	1.4
LJUB	8	11	-16.5	1.1	16.6	0.4	11.0	1.2
LVIV	7	10	-17.0	1.4	15.9	0.6	8.8	1.8
LYSA	4	6	-16.2	2.7	17.1	1.2	9.8	3.2
MACI	3	3	-24.7	4.1	14.6	2.2	3.9	4.7
MALJ	4	6	-19.9	3.5	16.6	1.1	8.5	3.6
MATE	7	11	-18.9	0.3	19.0	0.1	13.0	0.4
MEDI	4	6	-18.6	3.7	18.1	1.1	9.3	3.7
METS	8	11	-16.0	0.3	14.8	0.2	8.6	0.6
MOPI	8	11	-14.9	1.0	17.3	0.4	10.7	1.2
ONSA	8	11	-13.6	0.2	14.8	0.1	9.4	0.4
PART	4	6	-19.2	2.7	15.1	1.1	10.0	3.1
PENC	8	11	-18.7	0.9	17.1	0.3	6.7	1.0
POL1	4	6	-14.2	2.8	14.9	1.0	11.9	3.4
POTS	7	10	-16.2	1.0	16.2	0.3	7.7	1.3
SBGZ	4	6	-14.1	2.4	18.3	0.8	11.9	2.6
SKPL	8	11	-16.4	1.2	16.8	0.5	8.1	1.5
SNIE	8	11	-14.0	1.0	14.9	0.4	5.9	1.3
SOFI	6	9	-18.4	1.6	18.1	0.7	5.8	1.7
STHO	8	11	-18.3	1.3	17.4	0.5	7.7	1.5
SRJV	4	6	-18.0	4.0	17.4	1.5	9.5	4.0
SULP	5	8	-17.6	1.7	16.0	0.8	8.6	2.2
TARP	4	6	-18.6	3.3	15.5	1.5	6.7	3.8
TIS3	5	9	-12.2	1.8	18.4	0.8	15.3	1.9
TUBO	5	10	-15.8	2.6	17.4	1.0	10.3	3.0
UNPG	3	4	-16.2	2.2	15.8	0.9	8.8	2.8
UPAD	5	6	-17.3	5.4	16.4	1.5	9.1	5.4
UZHD	8	11	-18.2	1.1	16.3	0.5	7.1	1.4
VAT1	3	3	-17.3	12.9	17.1	6.3	8.9	15.3
VRAN	5	8	-31.0	6.4	10.1	3.5	-10.3	7.3
WROC	4	6	-16.2	2.2	15.8	0.9	8.8	2.8
WTZR	6	9	-15.8	0.2	17.1	0.1	8.6	0.4
ZIMM	8	11	-14.0	0.4	18.6	0.2	9.9	0.5

Reference frame is ITRF2000. Velocities and their uncertainties are in mm/year.

stations to enable reliable referencing to ITRF. The CERGOP 2005 campaign included 95 sites.

The characteristics of combined solutions of the eight CEGRN observation campaigns are summarised in Table 1. For velocity estimation we used the ADDNEQ2 program of the Bernese GPS software, version 5.0 (Hugentobler et al., 2004). The solution was validated by an independent velocity estimation model developed at the Slovak University of Technology using the error and weighting scheme described of Hefty et al. (2004). The combination of CEGRN solutions from various epochs is referenced to both ITRF2000 and ITRF2005 by constraining coordinates and velocities of a set of selected IGS sites using their variances and covariances from the ITRF2000 and ITRF2005 solutions respectively (Boucher et al., 2004; Altamimi et al., 2007). The differences between the two reference systems are negligible from the point of view of geokinematics. The ITRF2000 velocities are used here.

The selection of the reference sites was determined by the requirement that their velocities are obtained from a combination of at least two space techniques (GPS and VLBI and/or SLR). This criterion is met by the IGS stations BOR1, GRAZ, KOSG, MATE, WTZR, ONSA and ZIMM, which were included in CEGRN epoch campaign processing. Velocities at 52 non-reference sites were then determined on the basis of 1014 coordinate observations. The estimated CEGRN velocities and their uncertainties expressed in a geocentric reference system are summarised in Table 2.

The uncertainties depend mainly on the time span of observations (sites with the longest observation history cover 11 years), then on the number of incorporated campaigns (from 3 to 8) and on the quality and repeatability of site epoch observations.

To obtain information about the intraplate velocity field, model velocities for Eurasia were removed from the estimated velocities. We used the APKIM 2000 (Drewes, 1998) plate motion model, which is based on VLBI, SLR and GPS observations. The resulting intraplate velocities (with the APKIM model velocities removed) and their RMS errors are summarised in Table 3 and in Fig. 3.

#### 4. Velocity field in a regular grid

As is evident from Fig. 3 the distribution of sites with known velocities is not uniform; also remarkable are the differences in uncertainties of velocities at individual sites. To obtain information suitable for geo-kinematical modelling we interpolated the discrete velocities to a regular grid. Grid spacing must be defined consistently with the data distribution and the uncertainties.

For horizontal velocity interpolation we used a least squares collocation. The covariance of the velocities can be approximated by a function  $C(d)$

$$C(d) = \sigma_{0s}^2 \exp(-c^2 d^2) \quad (1)$$

where  $d$  is spherical distance between the measured and interpolated points expressed in degrees,  $\sigma_{0s}^2$  is the variance of the velocities and  $c$  is the reciprocal of the scale distance for decorrelation of velocity pairs. The exponential covariance is normally

Table 3

Velocities of CEGRN sites observed more than 3 epochs evaluated in the reference frame ITRF2000 reduced with the APKIM model and expressed in the local coordinate system East, North

Site	$v_n$	$\sigma_n$	$v_e$	$\sigma_e$
BASO	3.6	1.1	-2.8	1.0
BOR1	-0.3	0.2	0.6	0.2
BOZI	3.3	0.9	-0.7	0.7
BRSK	1.4	0.3	2.4	0.2
BUCA	-3.2	0.6	0.6	0.5
BUCU	-2.6	0.8	-0.4	0.6
BZRG	-0.3	0.9	-0.6	0.7
CSAN	-0.1	1.0	0.5	0.9
CSAR	0.7	0.4	0.3	0.3
DISZ	-0.9	0.4	2.8	0.3
DRES	1.3	0.8	0.1	0.6
DUBR	2.7	1.7	-1.5	1.3
FUN3	-5.2	1.0	-0.7	0.8
GILA	-1.3	1.2	0.0	0.9
GOPE	-0.1	0.3	0.9	0.2
GRAZ	0.4	0.2	1.1	0.1
GRMS	1.0	1.9	4.3	1.4
GRYB	-0.1	0.3	0.2	0.3
HARM	-3.2	0.5	0.4	0.4
HFLK	0.0	0.5	0.4	0.4
HOHE	1.9	0.3	-0.9	0.2
HUTB	0.7	0.6	1.7	0.5
HVAR	3.7	0.5	3.0	0.4
IAS3	2.5	1.0	0.7	0.8
JOZE	-0.2	0.3	0.8	0.3
KAME	-0.5	0.9	0.5	0.7
KIRS	0.7	0.8	0.7	0.6
KOSG	0.3	0.2	0.2	0.1
LAMA	-0.4	0.3	-0.6	0.3
LJUB	1.9	0.3	-0.8	0.3
LVIV	-0.5	0.4	-0.3	0.3
LYSA	0.1	0.9	0.5	0.8
MACI	0.8	1.1	1.0	0.8
MALJ	2.7	0.9	-0.2	0.7
MATE	4.1	0.2	1.1	0.1
MEDI	2.3	1.0	0.6	0.7
METS	-1.4	0.2	1.0	0.2
MOPI	0.0	0.3	0.0	0.2
ONSA	-0.8	0.1	-0.1	0.1
PART	2.9	0.9	-0.7	0.6
PENC	-0.3	0.3	0.9	0.2
POL1	0.9	0.9	-2	0.7
POTS	0.0	0.3	0.4	0.3
SBGZ	0.7	0.8	0.7	0.6
SKPL	-1.0	0.4	0.1	0.3
SNIE	-3.1	0.4	-1.9	0.3
SOFI	-2.3	0.5	0.7	0.4
SRJV	1.0	1.0	0.1	0.8
STHO	0.0	0.4	1.1	0.3
SULP	-0.2	0.5	0.0	0.4
TARP	-0.4	0.9	-0.5	0.7
TIS3	0.4	0.5	-1.0	0.4
TUBO	0.5	0.9	0.6	0.6
UNPG	-2.1	1.7	-2.0	1.4
UPAD	1.6	1.3	-1.1	1.0
UZHD	-0.6	0.4	0.2	0.3
VAT1	-0.8	2.4	0.3	1.7
VRAN	-3.2	2.1	-0.2	1.6
WROC	0.1	0.8	-0.4	0.6
WTZR	0.0	0.1	0.3	0.1
ZIMM	0.4	0.2	0.7	0.2

Units are mm/year.



Fig. 3. Intraplate horizontal velocities with  $2\sigma$  error ellipses, obtained from CEGRN velocities by removing the corresponding APKIM 2000 velocities.

used because it is finite and has zero derivative at the origin, is isotropic and has a minimum of adjustable parameters.

A best fit to the variogram of the velocities yields  $\sigma_{0s} = 2$  mm/year and  $c = 0.35$  degree<sup>-1</sup>. The graphical representation of the used covariance function is in Fig. 4. The characteristic distance of decorrelation of approximately 300 km agrees with earlier independent estimates in the Alpine Mediterranean area, and with the flexural wavelength of a 30 km thick crust (Caporali et al., 2003; Caporali, 2006).

Application of the least squares collocation method to the interpolation of horizontal velocities  $\mathbf{v}_{\text{pred}}$  is based on the simple relation

$$\mathbf{v}_{\text{pred}} = \mathbf{C}_S \mathbf{C}_v^{-1} \mathbf{v}_{\text{obs}} \quad (2)$$

where  $\mathbf{C}_S$  is covariance matrix of signal, and  $\mathbf{v}_{\text{obs}}$  is the vector of CEGRN velocities reduced for APKIM and for a mean value, and  $\mathbf{C}_v$  is their covariance matrix. The mean velocity is restored after interpolation. The geographical distribution of sites with CEGRN velocities as well as their uncertainties is inhomogeneous, so the optimum choice of grid for interpolated velocities is not trivial. We choose a (East  $\times$  North)  $2^\circ \times 1^\circ$  grid, as a compromise between data density and spatial resolutions over most of the study area.

Fig. 5 shows the interpolation on the  $2^\circ \times 1^\circ$  grid. The interpolation procedure takes rigorously into account the uncertainties and stochastic relationships among the observed velocities, so that error ellipses of the interpolated velocities, not shown in the figure, can also be estimated.

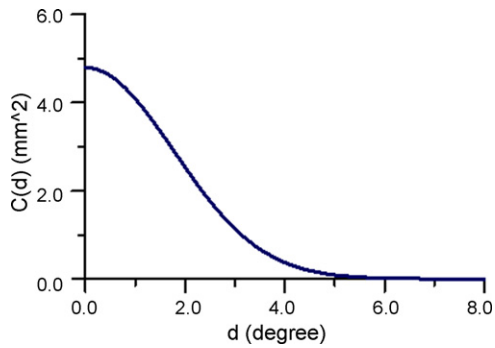


Fig. 4. Covariance function of signal used for interpolation of CEGRN velocity field.

## 5. Discussion

### 5.1. Adria, Dinarides and Pannonian Basin

The Adria microplate is the most active, fastest moving, major source of tectonic stress that dominantly shapes the deformation of South Central Europe. The independence of Adria from Nubia and Eurasia was tested and proved; F-ratio tests (Stein and Gordon, 1984) were performed for several subsets of sites believed to be on Adria. The two-plate model

assumption Adria–Eurasia turned out to be valid for all of the tests; their motion and boundaries were also outlined and suggested further fragmentation (Ward, 1994; Calais et al., 2002; Grenerczy et al., 2005). The strain distribution along the Italian part was further analyzed by Caporali et al. (2003) and the extensional strain across the Appenines was determined (Hefty, 2005). Fig. 3 shows that the CEGRN stations MATE, DUBR, HVAR and SRJV in the Adriatic region have well constrained velocities and the general convergence towards the Dinarides is clearly depicted in Fig. 6. A much more detailed picture will benefit from the upcoming 20 Bosnian GPS sites (Mulic et al., 2006) and a few additional sites in Serbia.

The stations in the northern part of the Adriatic Sea (MEDI, UPAD, BASO, LJUB, MALI) define a dominant velocity in a northerly direction with an average magnitude of 2 mm/year. The Austrian stations GRMS, SBGZ and GRAZ show eastward velocities, consistent with earlier results (Grenerczy et al., 2000, 2005; D'Agostino et al., 2005; Vrabec et al., 2006; Caporali et al., 2006). Accordingly, stations within, or near, the Pannonian Basin have velocities about 2 mm/year generally oriented to the east (HUTB, DISZ, PENC, STHO, KAME).

The Adria microplate appears as a wedge intruding into the southern part of the Eastern Alps, and causing a lateral,

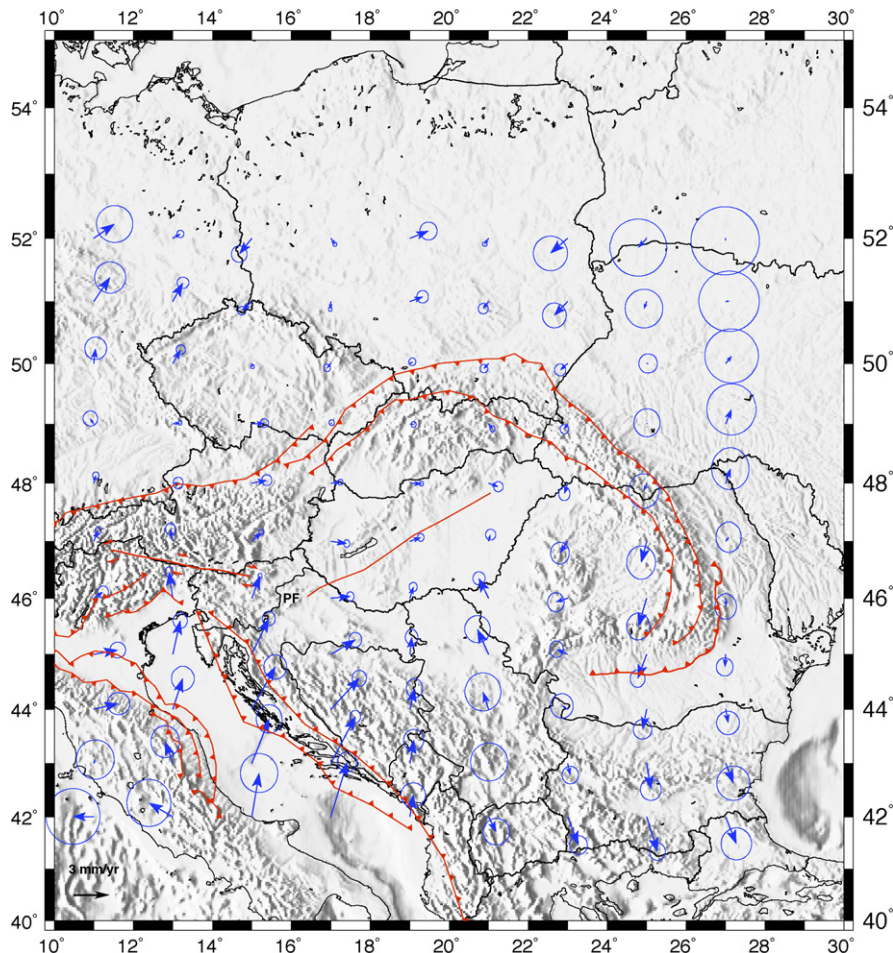


Fig. 5. Interpolation of CEGRN horizontal velocities into  $(E \times N) 2^\circ \times 1^\circ$  grid, by least squares collocation. Error ellipses are  $1\sigma$ . PF indicates the Pannonian fragment, defined by a Moho uplift of some 10 km (Brückl et al., 2007).



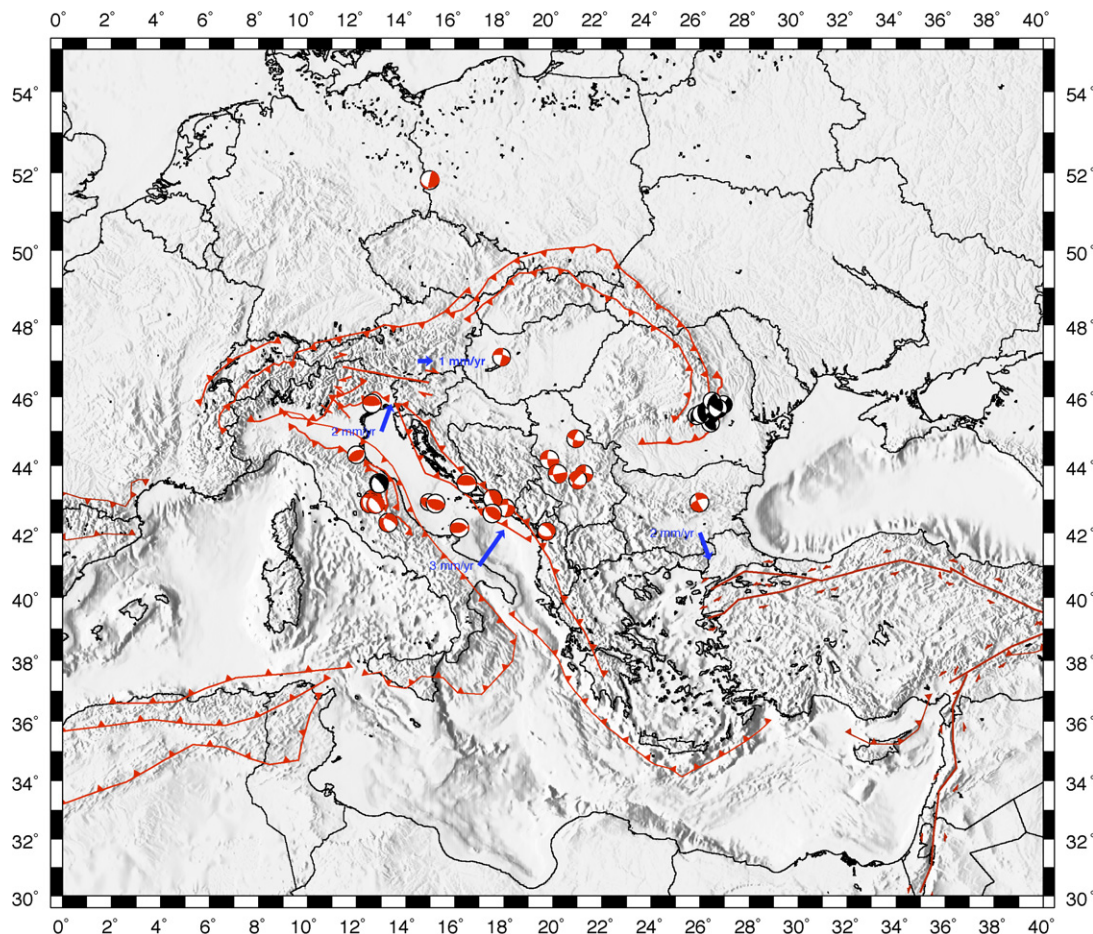


Fig. 6. Kinematical interpretation representing the closure of the Southern Adria towards the Dinarids, the northwards indentation of the Adria plate fragment, the eastward escape of the Tauern window towards the Pannonian basin, and the southward stretching of the Bulgarian–Rumanian crust. The drag of the Anatolian plate, which counterrotates relative to the Eurasian plate, is a likely explanation. Focal mechanisms are in red for depths up to 35 km, in black for deeper earthquakes.

eastwards extrusion towards the Pannonian Basin acting as an unconstrained stress sink. Recent results in seismic profiling have evidenced a vertical step of the Moho at the transition between the Alpine and Pannonian domains, suggesting the existence of a Pannonian plate fragment (Brückl et al., 2007). The lateral flow describing the extrusion is clearly visible in Fig. 6 and it appears rather continuous. Hence, if the hypothesis of a Pannonian plate fragment is justified from the crustal viewpoint, this cannot yet be confirmed from the kinematical viewpoint with the available data. The Alpine and Pannonian domains seem to share the same velocity pattern and an Eulerian pole specific for the Pannonian plate fragment seems at present unnecessary.

Moving further north of parallel 48°N, the velocities become small and randomly oriented, suggesting that a kinematically ‘stable’ European platform starts roughly north of the Carpathians.

### 5.2. The Carpathian arc

The CEGRN network has several sites in this region operating since 1995. Balkan stations situated in Bulgaria (SOFI, HARM) and Romania (MACI, BUCU, BUCA) have velocities oriented to the south and southeast. SOFI and BUCU/BUCA

belong to the EUREF network and are well constrained. The magnitude of velocities ranges from 2 to 4 mm/year and all the vectors exceed the  $2\sigma$  intervals. Other Romanian stations (MACI, IAS3, TIS3) have a shorter tracking history. Because of their uncertainty comparable or larger than the estimated velocity, they are treated as random noise by the collocation filter. Fig. 5 shows a number of interesting features of the velocity field in the Eastern Carpathians, Transylvania and the Wallachian region that includes the border between Bulgaria and Rumania. In Transylvania the velocities appear significantly different from zero, suggesting that this area, located just west of the Vrancea Seismic Zone, could be subject to active deformation. South and east of the Carpathian Arc, velocities increase by approximately 2 mm/year across a 600 km profile as one moves south (Fig. 6), indicating a long wavelength extensional regime. Previous measurements (Kotzev et al., 2001, 2006), based on 4 years of data (1996–2000), gave preliminary indications that an extensional regime characterizes the Wallachian area, southwards to the Hellenic arc. Our data confirm that the area south of the Carpathians is undergoing active stretching because of a positive gradient north to south. This stretching seems to decrease moving west, where the velocity field gradually decreases (Burchfiel et al., 2006) and then reverses its direction in the area of

Macedonia and Albania, suggesting an area of right lateral shear. The combination of the CEGRN data with the Italian and Greek data could shed more light on this area of active deformation.

## 6. Conclusions

The data we have presented cover a sizable part of Central and Eastern Europe where deformation and seismicity are moderate. Consequently, to discriminate a geokinematic signal out of noise requires a network such as CEGRN. We are able to confirm previous knowledge, and add some new results. With reference to Fig. 6, the interaction of Adria with the Southern Alps and the Dinarides involves contraction in different directions, N–S in the first case and SW–NE in the second case. The velocity drops by a factor of two, the north-east drift towards the Dinarides involving a larger slip rate, as high as 3.5–4 mm/year. The eastwards tectonic motion towards the Pannonian Basin is continuous and involves small velocity drops, of the order of 1–1.5 mm/year. This continuity at the surface is not mirrored at the depth of the Moho, where a jump suggests a Pannonian plate fragment separated from the Alpine domain. Overall velocities are small and random north of the 48°N, which can be considered stable in the sense that there is no consistent, collective kinematics. A N–S velocity pattern suggests a stretching crust in the area of Romania and Bulgaria. This stretching is not incompatible with reverse faulting seismicity in the Vrancea Seismic Zone. Earthquakes there take place at intermediate depths, and decoupling between crustal stretching at the surface and convergence below is implied. The cause for this long wavelength stretching of the crust, which is aseismic in the sense that it is not accommodated by one or more active faults, is to be found in a coupling with the counter rotation of the Anatolian block, resulting in a dragging effect. Hence, the convergence with the Nubia plate in the Hellenic arc has a long wavelength tail which extends just south of the Carpathian arc. Geophysical indicators of stress (Fig. 2) are patchy in this area, but where they exist they appear compatible with an extensional regime. Hence, models of Quaternary tectonics of Central and Eastern Europe should consider the portion of Europe north of the Carpathians as moving rigidly. The Alpine Carpathian Pannonian region is undergoing active deformation, as well as the Romanian–Bulgarian upper crust with its long wavelength, nearly aseismic deformation profile likely to be controlled by the motion of Anatolia and convergence with the Nubian Plate in the Hellenic arc.

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