



# Article Ballistic Limit Equation Derivation for Thin Tape Tethers

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Abstract: Electromagnetic tethers of hundreds or thousands of meters have been proposed for maneuvring spacecraft in Low Earth Orbit, and in particular, for post-mission disposals. The debate on tether survivability to debris impact is still influencing further advances in the implementation of such technology because of the large area they expose to the debris environment; thin tape geometries have been proposed instead of round ones to increase the survivability to hypervelocity impacts. In this context, this paper introduces a new Ballistic Limit Equation (BLE) for thin tape tethers, derived from experimental results, numerical simulations, and literature data. The resulting equation is non-monotonic with respect to impact angle, presenting a minimum depending on the debris velocity and size; for high obliquities, the debris fragmentation triggered by shock waves propagating into the material reduces the damage. This feature allows to set a minimum particle diameter for risk assessment, excluding a significant part of the debris flux. The proposed BLE confirms the performance of thin tape tethers, with respect to round wires, due to their better ballistic response as well as their reduced cross-section at high-obliquity impacts.

Keywords: tape tethers; ballistic limit equation; hypervelocity impacts

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# 1. Introduction

Tether systems for space have been proposed since the 1970s [1]; they consist of long cables or wires connecting orbital bodies (e.g., satellites, rocket stages, probes) that can be used, among others, for orbital maneuvring, momentum exchange, and attitude control. The first electromagnetic tether was tested on board the Space Shuttle in 1992 [2], as a joint collaboration between NASA and the Italian Space Agency. To date, different concepts have been proposed involving tethered spacecraft [3], with applications spanning from on-orbit servicing operations [4,5] to orbit transfer [6-8]; in particular, with regards to electromagnetic tethers, deorbiting devices have been investigated [9,10] or are under development [11,12]. A partial list of the most recent tether missions include TEPCE, that was partially successful in deploying a 1 km long tether with a 3U CubeSat splitting in two halves [13], the STARS mission by JAXA, testing different tether technologies [14], and the MiTEE demonstration mission [15]. In addition, the E.T.Pack project, funded by the European Commission, aims to develop and launch a technology demonstrator of a tether-based post-mission disposal kit before 2027 [16]. Other recent works focus on the development of safe and reliable technologies for the deployment and stabilization of space tethers [17-20].

One of the potential drawbacks for the widespread employment of tethers is the open debate on their survivability in the near-Earth space environment [21], and, in particular, their response to hypervelocity impacts (HVIs); tether lengths (up to kilometers) and their potential operational lifetime (up to years) make such devices particularly susceptible to debris impact. Previous investigations on tether damage were mostly focused on round wire geometries, providing a first estimation of their ballistic limit, assuming that

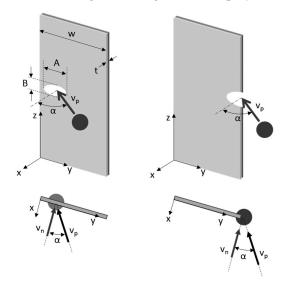
the damage volume depends on the debris kinetic energy [22–24]. To improve tether survivability to HVIs, thin tape geometries have been proposed instead of the classic round wire ones [25,26]; in addition, for tapes, charged particles collection from the magnetosphere is enhanced by the larger active area. The investigation of tape tether response to HVIs and, in particular, of the effect of impact orientation on the tapes has already been partially addressed [27,28], suggesting better survivability of this configuration. This theme will be further elaborated in this work.

Ballistic Limit Equations (BLEs) are employed in the space sector to assess the survivability of structures or components to collisions with space debris; they define the threshold particle size that would cause perforation or failure as a function of other impact parameters (e.g., impact velocity, impact angle, projectile and target materials and geometry) [29]. In general, they are represented as demarcation lines between no-perforation and perforation regions; as a function of the expected debris environment, they help to assess the failure risk of a component, therefore driving and constraining the design of a space mission. In this paper, a new empirical Ballistic BLE for thin tape tethers is introduced and its development is described; it provides the minimum particle diameter d<sub>crit</sub> to produce tether failure (cut-off) at a given projectile speed and impact angle. The work is performed for two investigated materials, polyether ether ketone (PEEK) and aluminum Al-1100-H19. The remainder of this paper is organized as follows: The method used for tape damage modeling and BLE development is summarized in Section 2; a description of the experimental results and numerical simulations is then given in Section 3. Sections 4-6 introduce the damage models, respectively, for low impact angles (4 and 5) and high obliquity (6). Finally, BLE derivation and uncertainty calculation are discussed in Section 7.

#### 2. BLE Development and Verification Method

#### 2.1. Impact and Tape Tether Geometry

The tape tether geometry investigated in this work can be seen in Figure 1, left: in the case of an impact with a debris with velocity  $v_p$ , a damage ellipse is defined by two axes, A and B. An "edge impact", visible on the right, occurs when the projection of the projectile is not contained in the tape surface, causing a damage on its edge. The tether length (i.e., in the *z*-direction) is not considered a relevant parameter for this study, as it can be considered infinite (tens to thousands of meters) with respect to the debris size (a few millimeters) in the space application; in the experiments reported in Section 3, such length was about two orders of magnitude larger than the projectile size.



**Figure 1.** Tape tether geometry and reference frame for impacts (**left**); edge impact (**right**). A and B are the damage ellipse major and minor axes,  $v_n$  is the projection of the debris velocity  $v_p$  on the normal to the tape.

### 2.2. Damage Model

Before introducing the BLE development approach, it is necessary to introduce the damage model employed in this work. It has been observed that, for quasi-normal impacts, the response of a thin tape to HVIs is equivalent to that of a thin plate—a spherical projectile creates a circular perforation hole (elliptical for non-normal impacts), with a diameter comparable to the projectile, with a well-defined and continuous circumference and minor or negligible material accumulation on the hole border. For the aforementioned reasons, in addition to dedicated experimental tests and numerical simulations data [27,28], literature data and models for thin plate perforation have been included in this work. This approach allows investigating the proposed model at tape thicknesses not directly investigated in the referenced works [28].

As reported by Abbas et al. [30], thin metallic plate impacts have been modeled by many authors, considering the projectile and the target density and the geometric dimensions as well as the impact velocity and direction. In particular, Hill [31] proposed a model for the perforation hole diameter reported in Equation (1) and compared it with relevant historical impact data [32–35]:

$$d_h = 3.309 \cdot d_p \cdot \left(\frac{v_p}{c_p}\right)^{0.033} \cdot \left(\frac{v_p}{c_t}\right)^{0.298} \cdot \left(\frac{\rho_p}{\rho_t}\right)^{0.222} \cdot \left(\frac{t}{d_p}\right)^{0.359} \tag{1}$$

where subscripts *h*, *p*, and *t*, respectively, indicate the perforation hole, the impacting projectile, and the impacted target. The main difference between Hill's model and this study case is the different thickness of the target, that in his case can be sixty times the one investigated in this work (up to 3.175 mm for Hill, 0.05 mm for the experiments reported in Section 3); furthermore, the model reported in Equation (1) does not consider the influence of the impact angle. However, the  $d_p/t$  ratios that can be found in Hill's work (from 2 to 12) are in a more comparable range with the tape experimental data (30 and 46).

Similarly, Sorenson [36] and Piekutowski [37] propose a model for the hole diameter based on the hypothesis that when the target thickness *t* is small with respect to the debris, the hole diameter should be close to the debris one. In general, Piekutowski and Sorensen consider the minimum hole size to be equal to the debris diameter. Their model can be written as follows:

$$d_h = d_p \cdot \left[ 1 + K_1 \cdot \left(\frac{\rho_p}{\rho_t}\right)^{K_2} \cdot \left(\frac{t}{d_P}\right)^{K_3} \cdot v_P^{K_4} \right]$$
(2)

Reflecting these considerations, we propose two models for the damage, based on the previous equations but including a relation with the impact angle, as reported in Equation (3); then, we compare their application limits and reliability in terms of maximal errors. The first one, the Adapted Hill Model (AHM) is similar to Equation (1) and considers the damage as a function of the  $d_p/t$  ratio, the impact velocity, and the impact angle. The main difference is related to the absence of a totally linear dependence to the particle diameter, following the approach already presented by Francesconi for a first analysis of the experimental dataset [28]. The other one, the Adapted Piekutowski–Sorenson Model (APSM), is based on the same considerations and, in addition, assumes that the minimum size of the perforation hole should be equal to the projectile projection on the tape,  $d_p/\cos(\alpha)$ . The experimental results employed to develop this model are between 0° and 80°, while the literature data are limited to a maximum impact angle of 56.4°.

$$A = k_1 \cdot \left(\frac{d_p}{t}\right)^{k_2} \cdot v_P^{k_3} \cdot \cos(\alpha)^{k_4} \qquad (AHM)$$
  
$$A = \frac{d_p}{\cos(\alpha)} \cdot \left[1 + k_1 \cdot \left(\frac{d_p}{t}\right)^{k_2} \cdot v_P^{k_3} \cdot \cos(\alpha)^{k_4}\right] \qquad (APSM)$$

The dependence of Equation (3) on the material is not considered in this work as different coefficients  $k_i$  are independently calculated for the two investigated materials. In addition, the employed experimental and numerical results have been determined at

a constant tape thickness  $t_0$ . To include the dependence on the thickness, the equations have been modified with the addition of the  $(t/t_0)^n$  parameter, the influence of which is assessed by employing literature data on thin plates. The definition of the main parameters of Equation (4) is discussed in Sections 4 and 5.

$$A = k_1 \cdot \left(\frac{t}{t_0}\right)^n \cdot \left(\frac{d_p}{t}\right)^{k_2} \cdot v_P^{k_3} \cdot \cos(\alpha)^{k_4} \qquad (AHM)$$

$$A = \frac{d_p}{\cos(\alpha)} \cdot \left[1 + k_1 \cdot \left(\frac{t}{t_0}\right)^n \cdot \left(\frac{d_p}{t}\right)^{k_2} \cdot v_P^{k_3} \cdot \cos(\alpha)^{k_4}\right] \qquad (APSM)$$
(4)

Last, particular attention is paid to high-obliquity impact angles, in which the assumption of a flat plate cannot be satisfied, and debris fragmentation can influence the impact process; in this case, an additional dedicated model is developed (see Section 6).

### 2.3. Empirical Procedure for BLE Development

The procedure employed in this work to obtain the BLE is based on an empirical approach proposed by Francesconi [28]; this method has the advantage of making it possible to estimate the failure prediction uncertainty. It consists of four steps, and is applied, respectively, to the Al-1100 and the PEEK tapes in order to calculate the BLE coefficients and their uncertainty for both the tether materials, as follows:

- 1. Test data acquisition: hypothesizing an elliptical damage, high-resolution imaging from experimental samples allows to determine the perforation ellipse major and minor axes *A* and *B* (see Figure 1). In this work the experimental dataset is enriched by results from dedicated numerical simulations; the dependence form tape thickness is assessed using literature data.
- 2. Empirical derivation of the damage equation: correlations between the damage major axis *A* and the impact parameters (particle size and velocity, impact angle, tape dimensions) are evaluated and verified. The damage equation is in the form:

$$A = f_d(d_p, t, v_p, \alpha) \tag{5}$$

- 3. Empirical determination of the critical damage: *A*<sub>crit</sub> is determined based on available data or theoretical modeling as the maximal damage the tether could endure as a percentage of the tape width before failure in the y-direction (i.e., tether cut-off).
- 4. BLE derivation: by inserting the critical value  $A_{crit}$  in the damage equation and inverting it, the BLE can be obtained.

$$d_{crit} = f_d^{-1} (A_{crit}, t, v_p, \alpha)$$
(6)

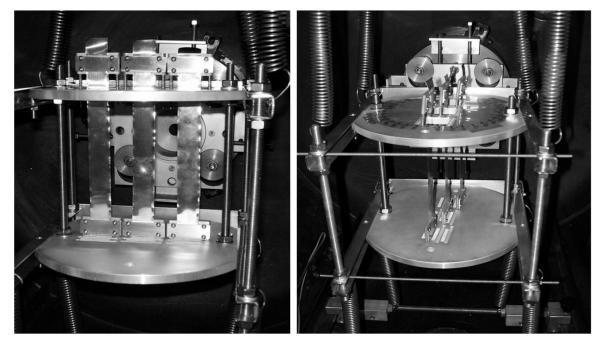
Usually, BLEs are presented as simple "demarcation lines" between fail and no-fail conditions, with no statistical significance [38]; by contrast, the key advantage of this method is that the BLE is given with uncertainty bands, thanks to the fact that both the damage equation  $f_d$  and the critical damage value  $A_{crit}$  are obtained mostly from experiments, and, hence, they can be related to suitable confidence intervals. All the available data, even well away from the ballistic limit, can, therefore, be used to statistically follow the critical parameter evolution. In this way, it is possible to provide an estimation of the test conditions at the ballistic limit, even inside the bounds defined by the two closest non-critical and critical experiments.

In this work, the value of *A* is obtained from experimental as well as numerical results. In parallel, a comparison with historical impact data from Hill [31] and Piekutovski [39] was employed to evaluate the effect of thickness and to validate the damage equations.

### 3. Experimental and Simulation Data

The experimental impact tests presented in this section were conducted at the CISAS G. Colombo Hypervelocity Impact Facility, using a two-stage light gas gun (LGG) capable of accelerating projectiles in the range 0.6–3 mm of diameter at speeds up to 6 km/s [40–42].

For the experimental campaign, a dedicated test setup was designed (see Figure 2); up to three tape samples were mounted in order to maximize the test success rate even at high-obliquity impacts. The possibility to orient the tapes as well as the LGG scattering allowed to define their orientation with respect to the projectile flight path with an accuracy up to  $\pm 1^{\circ}$ .



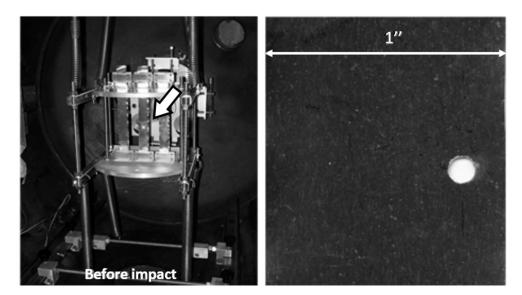
**Figure 2.** Tethers support structure mounted in the LGG impact chamber: On the left, the tape configuration is at  $\alpha = 0^{\circ}$ , on the right, tethers are oriented at  $\alpha \sim 90^{\circ}$  (high obliquity).

It must be underlined that the impact damage near  $90^{\circ}$  is highly dependent on the impact angle, and its evaluation is influenced by the angular uncertainty; therefore, for high-obliquity impacts, the ballistic limit equations determination required the utilization of numerical simulations results.

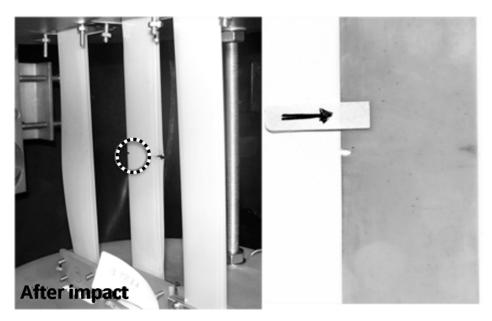
### 3.1. Test Results

During the experimental campaign, 24 hypervelocity impact tests were performed, varying the projectile speed and impact orientation, on Al-1100-H9 and PEEK tapes with a thickness of 0.05 mm and width of 25 mm [28]. Aluminum spherical projectiles were employed in the campaign; among the tests, 22 were performed with 1.5 mm projectiles and 2 with 2.3 mm ones. The results are summarized in Table A1 in Appendix A, with the ID identifying impact angles less than 80° (numbers) and at 90° (letters); edge impacts are indicated in grey. The result of two shots can also be observed in Figures 3 and 4, showing, respectively, a normal impact on Al-1100 and a 90° impact on PEEK.

From a preliminary inspection, it is possible to report that the tape damage, indicated by the value *A*, in conditions of normal impact is very close to the projectile diameter, but it increases with the impact angle. Furthermore, the two tape materials show a similar behavior; it is expected that the damage equations will be analogous in their form and coefficients.



**Figure 3.** Test no. 8856 (Al-1100-H19,  $\alpha = 0^{\circ}$ ): setup (**left**); detail of the tape damage (**right**).



**Figure 4.** Test no. 8871 (PEEK LITE,  $\alpha = 90^{\circ}$ ): setup with highlighted the damage area (**left**); detail of the tape damage with a marker arrow for analysis (**right**).

### 3.2. Numerical Simulations

Numerical simulations were conducted using ANSYS AUTODYN 3D on a multicore with CPU Intel I7 920@2.67 GHz processor and 6 GB RAM. The standard testbed consisted of a spherical Al-1100 projectile impacting on a tape 25.4 mm wide and 0.05 mm thick; the tape was discretized in mesh of about 0.13 mm. For tests with  $\alpha = 90^{\circ}$ , the projectile diameter was raised up to 15 mm and the tape thickness and width, respectively, to 0.50 mm and 35 mm, and, hence, the mesh was increased up to 0.5 and 1 mm after some validation versus simulation runs with better discretization. Further information can be found in [28]. The simulation parameters as well as the damage extension are reported in Appendix B in Table A2 ( $\alpha = 0$ –80°) and Table A3 ( $\alpha$ ~90°). Since the tether structure and the behavior of the materials employed for its construction are known fairly well, quite reliable results were expected. A total of 112 runs were performed ( $\alpha$  from 0° to 80° and  $\alpha$ ~90°) on both materials; about 30 simulations were interrupted close to the end, and a prediction of an approximate final result was formulated. For the sake of completeness, these results are included in

the report tables and highlighted, although they are not reliable enough to be used in the BLE development.

### 4. Damage Equation Derivation and Verification ( $\alpha = 0-80^{\circ}$ )—Adapted Hill Model

The damage equation for the range 0–80°, reported in Equation (4) (AHM), describes the tether damage as a function of the main geometrical parameters. Data from the experiments and simulations, as well as additional experiment data from the literature, were employed to derive the values of the damage equation coefficients for Al-1100 and PEEK. Results presenting  $v_n < 1$  km/s were weighted with the employment of a fragmentation correction coefficient  $\sigma$ , as proposed by Francesconi [28]. For the sake of completeness, the justification for employing such correction is reported here. The dependence of the model on the angle causes the derived equation to have a vertical asymptote for  $\alpha = 90^{\circ}$  (i.e., the damage parameter A tends to infinity), clearly not representing the physics of highly oblique impacts. As represented in Figure 5, with increasing impact angle, the normal velocity  $v_n$  decreases with respect to the velocity of shock waves propagating inside the debris (top); under a threshold value  $v_{n,thr}$ , the shock wave can fragment the debris before it fully interacts with the tether (bottom), letting pieces bounce on the tape surface and reducing the damage with respect to the prediction. Due to this phenomenon, the proposed models reported in Equation (4) cannot fully represent the fragmentation process.

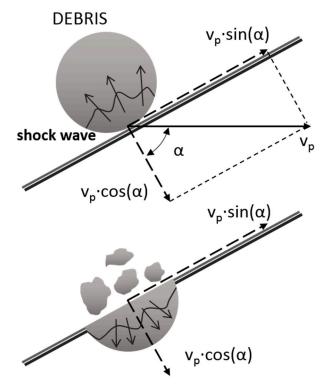


Figure 5. Debris fragmentation upon highly oblique impact.

Francesconi et al. [28] propose use of an empirical fragmentation correction coefficient  $\sigma$  to apply to the debris diameter  $d_p$ , that can be defined as follows:

$$\sigma = \frac{1}{1 + exp\left[-k_5 \cdot \left(v_p \cdot \cos\alpha - k_6\right)\right]} \tag{7}$$

The values of the two coefficients are reported in Table 1. In particular,  $k_6$  represents the characteristic velocity of the investigated material and is proposed as an indirect value for the threshold velocity  $v_{n,thr}$ .

Parameter	Al	-1100	P	EEK
	Value	Standard Deviation	Value	Standard Deviation
$k_5$	6.37	1.97	5.00	1.62
<i>k</i> <sub>6</sub> , km/s	0.52	0.40	0.15	0.10

Table 1. Fragmentation parameters for Al-1100 and PEEK (Adapted from [28]).

Starting from these considerations, a non-linear fitting was performed using test, simulation, and literature data, as well as the fragmentation coefficient  $\sigma$ . Literature data allowed investigating target thicknesses different from the test and simulation ones  $(t_0 = 0.05 \text{ mm})$ , leading to generalization of the proposed model AHM. This generalization can be written as:

$$A = k_1 \cdot \left(\frac{t}{t_0}\right)^n \cdot \left(\frac{d_p}{t}\right)^{k_2} \cdot v_P^{k_3} \cdot \cos(\alpha)^{k_4}$$
(8)

The calculation of the coefficient n was performed using available historical data on aluminum thin plate impacts by Hill [31] and Piekutowski [39], considering  $d_v/t$  ratios comparable to the studied one. A threshold was defined at  $d_p/t = 5$ , allowing to obtain the parameter n = 0.8759; therefore, Equation (8) is rewritten in a simpler version in Equation (9), with the five coefficients reported in Table 2:

$$A = k_{11} \cdot d_p^{k_2} \cdot t^{k_{22}} \cdot v_P^{k_3} \cdot \cos(\alpha)^{k_4}$$
(9)

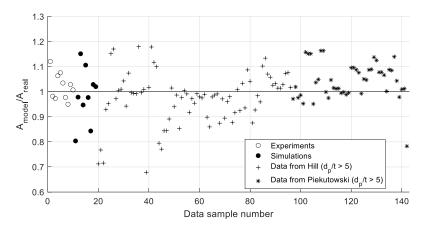
Demonstra	Al-1100	PEEK
Parameter ——	Value	Value
k <sub>11</sub>	2.9815	2.2299 *
k <sub>2</sub>	0.6223	0.6460
k <sub>22</sub>	0.2536	0.2299 *
k <sub>3</sub>	0.0927	0.1577
k <sub>4</sub>	-0.7460	-0.7637
R <sup>2</sup>	0.9508	0.9530
$\sigma_{FIT}$	9.76%	14.93%

Table 2. Equation parameters for Al-1100 and PEEK (AHM—final model).

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It must be underlined that this generalization is valid for the Al-1100 model. PEEK parameters were derived using the same value of *n*, and the obtained model, still valid for the investigated tether geometrical parameters, will require further investigation to evaluate the influence of the tape thickness.

In Figure 6 the proposed damage model is compared with the available data from the tape experiments and simulations and from historical data. It must be underlined that the fit standard deviation for this case is less than 10%.

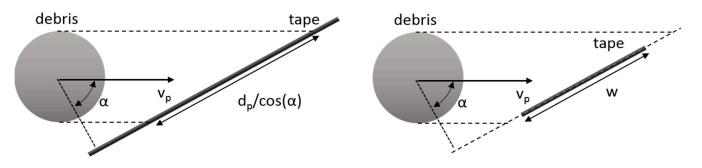


**Figure 6.** Comparison between AHM model and results available from tape experiments and simulations (circular marks) and from thin plate historical data (data from Hill [31], Piekutowski [39]).

### 4.1. Damage Equation Outside the Test Range $(dp/cos(\alpha) > w)$

The aforementioned damage model was developed comparing the tape to a thin plate, a condition that can be considered satisfied for small debris (Figure 7, left); however, there are configurations in which such a hypothesis cannot be confirmed, i.e., when the debris diameter projection on the tape is larger than the tether width (Figure 7, right). Therefore, the model needs to be adapted to this new configuration; a proposed solution is reported in Equation (10), substituting the debris projection  $d_v/cos(\alpha)$  with the tether width.

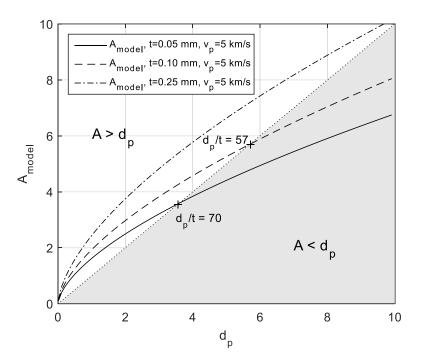
$$A = \begin{cases} k_{11} \cdot d_p^{k_2} \cdot t^{k_{22}} \cdot v_p^{k_3} \cdot \cos(\alpha)^{k_4} & d_p < w \cdot \cos(\alpha) \\ k_{11} \cdot w^{k_2} \cdot t^{k_{22}} \cdot v_p^{k_3} \cdot \cos(\alpha)^{k_4 - k_2} & d_p > w \cdot \cos(\alpha) \end{cases}$$
(10)



**Figure 7.** Geometrical projection of the debris diameter on the tape surface: in the test range case, the tape width is larger than the projection (**left**); on the (**right**), the debris projection is larger than *w*.

### 4.2. Limitations of Adapted Hill Model

Despite the good results from the AHM, some issues were highlighted on its range of applicability. The model is based on experimental and simulation data with a ratio  $d_p/t$  in the range 10–46 and it is improved with available literature data from thin plates ( $d_p/t$  in the range 5–35). For this reason, it is expected that for higher  $d_p/t$  ratios ( $d_p/t > 50$ ), the model could have lower precision. In particular, Figure 8 shows that for larger debris sizes, the AHM tends to underestimate the damage when it becomes smaller than the debris diameter. For this reason, this model is suggested only for tapes with a small w/t ratio (i.e., w/t < 100), for which large values of  $d_p/t$  could be reached only for debris with a diameter comparable to the tape, that would already cause damage wide enough to sever it.



**Figure 8.** Comparison of debris size and damage prediction with AHM (normal impacts); large  $d_p/t$  ratios may cause damage underestimation for large debris size.

Based on these considerations, the following Adapted Piekutowski–Sorenson Model (APSM) model is proposed; thanks to its different formulation, it overcomes such limitations, allowing investigating the higher  $d_p/t$  ratios.

# 5. Damage Equation Derivation and Verification ( $\alpha = 0-80^{\circ}$ )—Adapted Piekutowski–Sorenson Model

The APSM, reported in Equation (4), describes the tether damage as a function of the test parameters, considering that for the highest  $d_p/t$  ratios, the damage tends to become equal to the debris diameter projection on the tape. The equation coefficients are again calculated with the introduced iterations process, starting from experimental data and considering the influence of fragmentation, and then adding simulations and corrected experimental results as well as the thin plate data from historical impact tests. For the sake of brevity, the whole process is not reported and only the final parameters are summarized in Equation (11) and Table 3:

$$A = \begin{cases} \frac{d_p}{\cos(\alpha)} \cdot \left[ k_{11} \cdot \frac{t^{k_{22}}}{d_p^{k_2}} \cdot v_p^{k_3} \cdot \cos(\alpha)^{k_4} \right] & d_p < w \cdot \cos(\alpha) \\ w \cdot \left[ k_{11} \cdot \frac{t^{k_{22}}}{d_p^{k_2}} \cdot v_p^{k_3} \cdot \cos(\alpha)^{k_4} \right] & d_p > w \cdot \cos(\alpha) \end{cases}$$
(11)

Again, it must be underlined that this generalization is valid for the Al-1100 model. The PEEK parameters were derived using the same literature dataset, and the obtained model, still valid for tether data, would require further investigation to evaluate the influence of the tape thickness. In all the aforementioned cases, it must be remembered that for low normal velocities, the damage size needs to be calculated using the correction parameter  $\sigma$ .

Description	Al-1100	PEEK
Parameter	Value	Value
k <sub>11</sub>	1.8352	1.3865 *
k <sub>2</sub>	0.9831	1.1940
k <sub>22</sub>	0.7477	0.9586 *
k <sub>3</sub>	0.5023	0.8012
k <sub>4</sub>	0.8264	6.6401
R <sup>2</sup>	0.9471	0.9708
σ <sub>FIT</sub>	10.49%	22.32%

Table 3. Equation parameters for Al-1100 and PEEK (APSM-final model).

\* derived from Al-1100 generalization.

In Figure 9, the proposed damage model is compared with the available data from tape experiments and simulations and from historical data. It must be underlined that the fit standard deviation for this case is less than 10.5%.

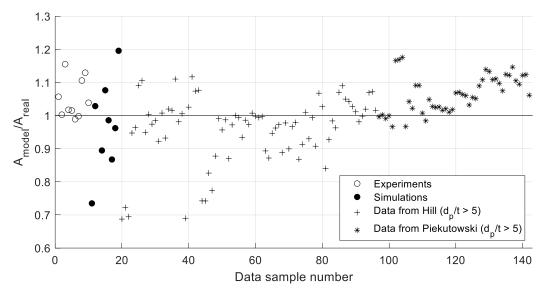
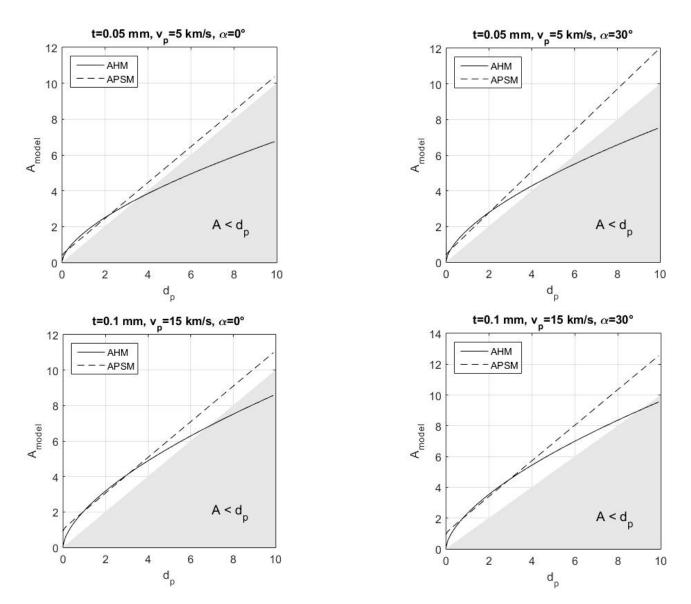


Figure 9. Comparison between APSM model and results available from tape experiments and simulations (circular marks) and from thin plate historical data (data from Hill [31], Piekutowski [39]).

### 5.1. Comparison with Adapted Hill Model

A brief comparison between the two elaborated models is reported here. Figure 10 shows that both the AHM and the APSM present similar behavior for small size debris at different thicknesses and velocities; it is determined that for values of  $d_p/t$  in the range from 5 to 35, the difference is less than 15% for thicknesses up to 0.5 mm. For larger particles, the two model predictions diverge: the APSM shows a linear trend and predicts a damage larger than the debris diameter, while the AHM damage prediction decreases below the particle size for large debris.



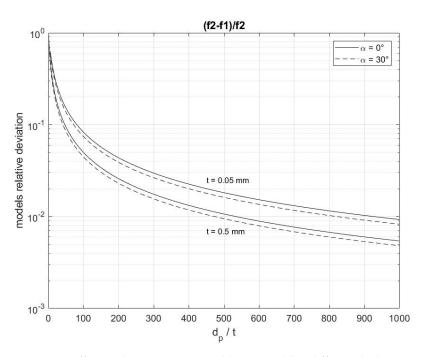
**Figure 10.** Comparison of damage prediction as a function of debris size for AHM and APSM, at different thickness, velocity, and impact angle.

## 5.2. Simplification for Large d<sub>p</sub>/t Ratios

Figure 10 clearly shows that at different values of thickness, velocity, and impact angle, the APSM presents a linear trend for large  $d_p/t$  ratios. The deviation between a linear model (i.e., depending only on the parameter  $d_p/\cos(\alpha)$ ) and APSM can be seen in Figure 11 and decreases under 10% for  $d_p/t > 100$ . Based on this consideration, it is possible to rewrite Equation (11) in an extremely simplified form:

$$A = \begin{cases} d_p / \cos(\alpha) & d_p < w \cdot \cos(\alpha) \\ w & d_p > w \cdot \cos(\alpha) \end{cases}$$
(12)

More precisely, the maximal deviations for Al-1100 and PEEK, calculated for a thickness of 0.05 mm and a  $d_p/t$  ratio of 100, are, respectively, 8.27% and 4.00%.



**Figure 11.** Difference between APSM and linear model at different thicknesses and impact angles; for  $d_p/t > 100$ , the relative deviation is under 10% for the investigated tape.

### 6. Damage Equation Derivation ( $\alpha$ ~90°)

For high-obliquity impacts ( $\alpha \sim 90^\circ$ ), numerical simulations were used to study the tape behavior. It must be considered that in this case the impact physics can be more complex than in the previous one, so a novel damage equation applicable for impact angle  $\alpha = 90^\circ$  is derived. The resulting formula is reported in Equation (13) and suggests that the damage at  $90^\circ$  is nearly independent of the impact velocity.

$$A = c_1 \cdot d_p^{\ c_2} \cdot t^{c_3} \tag{13}$$

The values of the fit parameters and their standard deviations are given in Table 4; it should be noted that the two tapes (Al-1100 and PEEK) show different behavior (i.e., different parameter values), but for both the cases, the dependence from the tape thickness is similar ( $c_3$  is about -1/4 for both the cases). With the values below, the fit correlation index is  $R^2 = 0.91$  for Al-1100 and  $R^2 = 0.97$  for PEEK; the fit standard deviation is  $\sigma_{FIT} = 29\%$  for Al-1100 and  $\sigma_{FIT} = 33\%$  for PEEK.

**Table 4.** Equation parameters for Al-1100 and PEEK ( $\alpha = 90^{\circ}$ ).

Parameter –	Al	-1100	PEEK		
	Value	Standard Deviation (%)	Value	Standard Deviation (%)	
<i>c</i> <sub>1</sub>	1.4637	5.23	1.3573	7.79	
c <sub>2</sub>	1.0032	1.0032 1.13		3.08	
<i>c</i> <sub>3</sub>	-0.2498 01.08		-0.2575 1.35		
$R^2$	(	0.91	0.97		
$\sigma_{FIT,90^\circ}$	2	29%	33%		

### 7. Ballistic Limit Equation for Tapes

Following the procedure introduced in Section 2, a ballistic limit equation can be obtained from the damage equations derived in Sections 4–6. It is worth underlining that the resulting BLE is a piecewise formula, since the different damage equations are applicable to different ranges of normal velocity  $v_n$ :

- (1) For  $v_n > v_{n,thr} = k_6$ , the BLE is derived from Equation (10) (AHM) or (12) (linearized APSM);
- (2) For  $v_n = 0$  ( $\alpha \sim 90^\circ$ ), the BLE is derived from Equation (13);
- (3) For  $0 < v_n < v_{n,thr} = k_6$ , the BLE is constructed linearly joining the value derived from Equation (13) to the one derived from Equation (10) or (12) for  $v_n = k_6$ .

Before elaborating the damage equations in the desired form, a critical value  $A_{crit}$  for the damage major axis shall be assumed; by definition, the tether is cut-off if  $A \ge A_{crit}$ . In general,  $A_{crit}$  can be different for the two materials and can be represented in the form:

$$\begin{cases} A_{crit}^{Al-1100} = k_{w,Al-1100} \cdot w \\ A_{crit}^{PEEK} = k_{w,PEEK} \cdot w \end{cases}$$
(14)

Equation (14) defines the critical damage as the minimum amount of material that has to be removed by the impact from the tether to cause the failure; the coefficients  $k_w$  are both smaller than 1, and have been calculated as the residual cross-section capable to withstand the tether loads, estimated as about 10 N of tensile load and (only for Al-1100) 2 A of electric current [28]. The values of the two coefficients are reported in Table 5 and were calculated considering the material properties at the maximum operative temperature expected for the tape tether. The lower value for Al-1100 is justified by the need to sustain both the mechanical and thermal load due to the current flow.

Table 5. Critical damage coefficients for the two investigated materials.

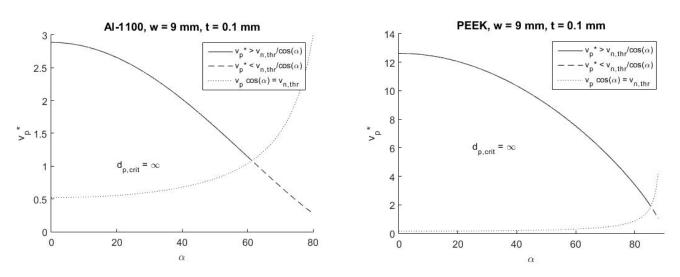
k <sub>w,Al-1100</sub>	k <sub>w,PEEK</sub>	
$0.80 \pm 0.10$	$0.90\pm0.10$	

7.1. BLE Derivation for  $v_n > v_{n,thr} = k_6$ —AHM

To obtain the BLE, the critical damage parameterization is inserted in Equation (10) and the resulting formula is inverted, as reported in Equation (15):

$$d_{p,crit} = \begin{cases} \left(\frac{k_{w} \cdot w}{k_{11} \cdot t^{k_{22}} \cdot v_{p}^{k_{3}} \cdot \cos(\alpha)^{k_{4}}}\right)^{1/k_{2}} & v_{p} > v_{p}^{*} = \left(\frac{k_{w} \cdot w^{1-k_{2}}}{k_{11} \cdot t^{k_{22}} \cdot v_{p}^{k_{3}} \cdot \cos(\alpha)^{k_{4}+k_{2}}}\right)^{1/k_{3}} \\ \infty & v_{p} < v_{p}^{*} = \left(\frac{k_{w} \cdot w^{1-k_{2}}}{k_{11} \cdot t^{k_{22}} \cdot v_{p}^{k_{3}} \cdot \cos(\alpha)^{k_{4}+k_{2}}}\right)^{1/k_{3}} \end{cases}$$
(15)

It should be noted that Equation (15) identifies a minimum debris velocity  $v_p^*$  below which no critical damage is possible. The value of  $v_p^*$  depends on the tape material and geometry, as well as the impact angle. Unfortunately, such values may not be acceptable, as the AHM model applicability is limited to a ratio  $d_p/t < 100$ , and the investigated values for tape failure rise to  $d_p/t >> 100$ . However, this model is still acceptable for predicting small damages or for tethers with small width ( $w/t \le 100$ ); as mentioned in Section 4, for such geometries, the damage model can be assumed to be valid. For example, Figure 12 shows for both Al-1100 and PEEK, the trend of  $v_p^*$  as a function of the angle for a tether of width w = 10 mm and thickness t = 0.1 mm. It can be observed that debris with velocity smaller than  $v_p^*$  do not critically damage the tape tether. The dotted line indicates debris velocity in the condition  $v_n = v_{n,thr}$ .



**Figure 12.**  $v_p^*$  trend for a 9 millimeter-wide tether at different impact angles for Al1100 (**left**) and PEEK (**right**).

The uncertainty of this BLE is estimated by propagating the uncertainties of the individual parameters  $k_i$ , using the classic method introduced by Kline and McClintok [43];  $\sigma_{FIT}$  is the standard deviation of the model, as reported in Table 2.

$$\frac{U_d^2}{d_{p.crit}^2} = \frac{U_{coeff}^2}{d_{p.crit}^2} + \sigma_{FIT}^2$$
(16)

$$U_{coeff}^{2} = \sum_{i} \left[ \left( \frac{\partial d_{p.crit}}{\partial k_{i}} \right)^{2} \cdot U_{k_{i}}^{2} \right]$$
(17)

Solving Equation (17), the uncertainty can, therefore, be rewritten as follows:

$$\frac{U_d}{d_{p.crit}} = \sqrt{ \frac{\left(\frac{1}{k_2 k_1}\right)^2 \cdot U_{k_1}^2 + \left[\frac{1}{k_2^2} \ln\left(\frac{k_w \cdot w}{k_{11} \cdot t^{k_{22}} \cdot v_p k_3 \cdot \cos(\alpha)^{k_4}}\right)\right]^2 \cdot U_{k_1}^2 + \dots} \\ \dots + \left(\frac{\ln(t)}{k_2}\right)^2 \cdot U_{k_{22}}^2 + \left(\frac{\ln(v_p)}{k_2}\right)^2 \cdot U_{k_3}^2 + \left(\frac{\ln(\cos\alpha)}{k_2}\right)^2 \cdot U_{k_4}^2 \dots \\ \dots + \left(\frac{1}{k_2 k_w}\right)^2 \cdot U_{k_w}^2 + \sigma_{FIT}^2$$
(18)

Equation (18) shows that the uncertainty depends mainly on the velocity, the thickness, and the impact angle. In Table 6, its value is reported both for Al-1100 and PEEK for three different impact speeds (two applicable to debris, one to meteoroids), for three different tape thicknesses.

Table 6. Uncertainty for d<sub>p,crit</sub> estimation for different thicknesses and velocities.

t, mm	Material	7 km/s	15 km/s	20 km/s
0.05	Al-1100	38.10%	38.09%	38.09%
	PEEK	21.55%	21.56%	21.56%
0.1	Al-1100	37.84%	37.83%	37.83%
	PEEK	21.55%	21.56%	21.56%
0.5	Al-1100	37.44%	37.43%	37.42%
	PEEK	21.55%	21.55%	21.56%

7.2. BLE Derivation for  $v_n > v_{n,thr} = k_6$ —Linearized APSM

The linearized APSM, reported in Equation (12), is rewritten in the form:

$$d_{p,crit} = k_w \cdot w \cdot cos(\alpha) \tag{19}$$

It is clear that such a formulation is totally independent from the tape thickness and the impact velocity, and unlike the AHM, it can be employed for tapes with w/t > 100.

Following the same procedure of Section 7.1, the uncertainty is calculated both for Al-1100 and PEEK and can be written as shown in Equation (20), in this case introducing also the linearization uncertainty  $\sigma_{LIN}$ ; the resulting values are reported in Table 7.

$$\frac{U_d}{d_{p.crit}} = \sqrt{\frac{U_{coeff}^2}{d_{p.crit}^2} + \sigma_{FIT}^2 + \sigma_{LIN}^2} = \sqrt{\frac{U_{kw}^2}{kw^2} + \sigma_{FIT}^2 + \sigma_{LIN}^2}$$
(20)

Table 7. Uncertainty values for the APSM.

	Al-1100	РЕЕК
$rac{U_d}{d_{p,crit}}$	18.29%	25.25%

7.3. BLE Derivation for  $v_n = 0$  ( $\alpha = 90^\circ$ )

The BLE for normal impacts, derived from Equation (13), can be written in the form:

$$d_{p,crit} = \left(\frac{k_w \cdot w}{c_1 \cdot t^{c_3}}\right)^{1/c_2} \tag{21}$$

The critical damage, therefore, depends only on the tape material and the geometrical dimensions. For the tether investigated in [28] (thickness of 0.05 mm, width of 25 mm), the value of the particle critical diameter is 6.53 mm for Al-1100 and 4.43 mm for PEEK. Again, the uncertainty formulation and values are reported in Equation (22) and in Table 8.

$$\frac{U_d}{d_{p,crit}} = \sqrt{\frac{\left(\frac{1}{c_2 k_w}\right)^2 \cdot U_{k_w}^2 + \left(\frac{1}{c_2 c_1}\right)^2 \cdot U_{c_1}^2 + \left[\frac{1}{c_2^2} \ln\left(\frac{k_w \cdot w}{c_1 \cdot t^{c_3}}\right)\right]^2 \cdot U_{c_2}^2}{\dots + \left(\frac{\ln(t)}{c_2}\right)^2 \cdot U_{c_3}^2 + \sigma_{FIT}^2}}$$
(22)

**Table 8.** Uncertainty values for the  $90^{\circ}$  model.

	Al-1100	РЕЕК
$\frac{U_d}{d_{p,crit}}$	32.07%	34.75%

7.4. BLE Derivation for  $0 < v_n < v_{n,thr} = k_6$ 

The BLE in this range is simply obtained by joining the previous models (AHM or APSM calculated in  $v_{n,thr} = k_6$  with the  $\alpha \sim 90^\circ$  model) with a linear function of  $v_n$ :

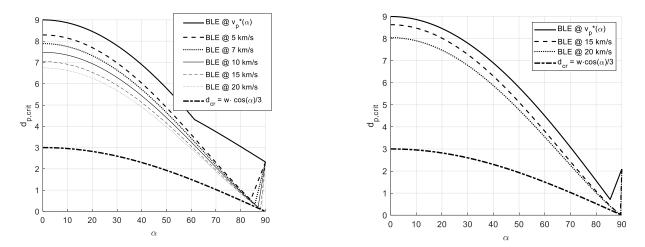
$$d_{p,crit} = v_p \cdot \cos(\alpha) \cdot \frac{d_{p,crit,v_{n,thr}} \cdot k_6 - d_{p,crit,90^\circ}}{k_6} + d_{p,crit,90^\circ}$$
(23)

The uncertainty can be obtained by joining with a linear function of  $v_n$  the uncertainty value calculated with the AHM or the APSM (for  $v_n = k_5$ ) to that calculated for  $\alpha \sim 90^\circ$ .

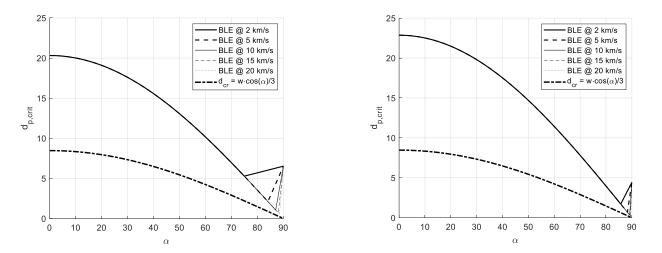
### 8. Results

The new piecewise BLE, described by the previous equations, is represented in Figure 13 (for w/t < 100) and Figure 14 (w/t > 100, study case in [27]), as a function of the

impact angle  $\alpha$  and for different impact velocities; in all the plots, the BLE is also compared to the classic assumption (for round wires, dash-dot line) that the critical damage can be caused by a particle with size around one-third of the tether equivalent diameter,  $w \cdot cos(\alpha)$ . In all the cases, the classic BLE is much more conservative, and this analysis demonstrates that tapes are much less vulnerable with respect to round wires.



**Figure 13.** Piecewise BLE for Al-1100 (**left**) and PEEK (**right**), as a function of the impact angle, for a tape having thickness 0.1 mm and width 9 mm (w/t < 100).



**Figure 14.** Piecewise BLE for Al-1100 (**left**) and PEEK (**right**), as a function of the impact angle for the investigated tape, where t = 0.1 mm and w = 25.4 mm (w/t > 100).

It also appears that both materials show similar behavior, considering that the critical damage coefficient  $k_w$  is greater for PEEK; the plots also show the influence of the different fragmentation thresholds, causing the Al-1100 BLE to vary its trend at lower impact angles.

Last, it is important to note the main effect of the BLE formulation for w/t < 100 (AHM, Figure 13) and for w/t > 100 (linearized APSM, Figure 14). In the first case, it is possible to appreciate the BLE dependence on the impact velocity, and a minimum value  $v_p^*$  can be determined below which no critical damage is caused; for higher velocities, a minimum value of  $d_{p,crit}^*$ , as a function of the impact velocity, can be determined, corresponding to the threshold to debris fragmentation. In the linearized APSM, it is instead possible to note that the BLEs are all overlapping before the fragmentation threshold, as the tape is so thin that the debris velocity does not influence the damage size; again, a minimum value of  $d_{p,crit}$  can be determined at the fragmentation threshold.

The possibility to determine these minimum values is an extremely important feature for the BLE, since it sets a minimum particle diameter for risk assessment, allowing to exclude a large part of the flux from risk computation. For example, in the case shown in Figure 14 (left), the investigated tape shows that  $d_{p,crit}^* = 5$  mm for an impact velocity of 20 km/s; almost all micrometeoroids are below this size, leading to the conclusion that, for this tether, micrometeoroids do not represent a serious threat. A formulation of  $d_{p,crit}^*$  is reported in Equation (24), in the condition that  $v_p \cdot cos(\alpha) = v_n = k_6$ .

$$d_{p,crit}^{*} = \begin{cases} \left(\frac{k_{w} \cdot w}{k_{11} \cdot t^{k_{22}} \cdot v_{p}^{k_{3}} \cdot \cos(\alpha)^{k_{4}}}\right)^{1/k_{2}} & w/t < 100\\ k_{w} \cdot w \cdot \cos(\alpha) & w/t > 100 \end{cases}$$
(24)

### 9. Conclusions

This paper presented the derivation of a new experimental ballistic limit equation for tapes, which represents a significant advancement in the state of the art with respect to previous equations developed for round wires, that are mainly based on geometrical considerations and limited experimental data and which neglect the damage dependence on the impact velocity and angle. By contrast, in this study, special care has been paid to the highly directional impact behavior of tapes.

The BLE derivation combined experimental results (HVI tests performed on tapes with fixed thickness and width) and numerical simulations with data from the state of the art, making it possible to estimate the uncertainty in the failure prediction. Two different damage models were proposed, the Adapted Hill Model (AHM) and the Adapted Piekutowski–Sorenson Model (APSM), investigating their validity; the first one showed a damage underestimation for the higher  $d_p/t$  ratios, so a linearized form of the latter was used for  $d_p/t > 100$ .

The resulting equation is non-monotonic with respect to the impact angle, presenting a minimum, depending on the debris velocity and size; for higher obliquities, the debris fragmentation triggered by shock waves propagating into the material reduces the damage on the tether.

Two different formulations were proposed for the BLE, depending on the width-tothickness ratio and derived from the AHM and the linearized-APSM. For w/t < 100, it was observed that there is a minimum value of debris velocity below which no critical damage is possible, and, furthermore, that there is a minimum velocity-dependent value  $d_{p,crit}$  \* of the debris diameter below which no critical damage is possible. For higher w/t ratios, the influence of the debris velocity and the tape thickness were considered negligible due to the larger debris size involved in tape failure; the tape is so thin that the debris velocity does not influence the damage size. Again, it was possible to determine a minimum value of  $d_{p,crit}$ \*, velocity-dependent, at the fragmentation threshold. This feature of BLE is extremely important, since it sets a minimum particle diameter for risk assessment.

Last, it is worth underlining that this study confirms that thin tapes are significantly more resistant than round wires of equivalent cross-section, thanks to the intrinsic ballistic response of tapes.

Further investigation should focus on high-obliquity impacts in order to model the fragmentation phase and improve the proposed damage model.

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# Abbreviations

Α	=	damage ellipse major axis, mm
В	=	damage ellipse minor axis, mm
BLE	=	Ballistic Limit Equation
С	=	sound velocity in the material, km/s
c <sub>i</sub>	=	BLE constant (high-obliquity impacts)
d	=	diameter, mm
f <sub>d</sub>	=	damage function
$K_i$	=	numerical constant in Sorensen and Piekutowski model
$k_i$	=	BLE constant
$R^2$	=	fit correlation index
t	=	tether thickness, mm
$t_0$	=	tether thickness in experiments, 0.05 mm
υ	=	velocity
w	=	tether width, mm
U	=	uncertainty
$v_n$	=	normal impact velocity, km/s
$v_p$	=	impact velocity, km/s
α	=	impact angle, $^{\circ}$
ρ	=	material density, kg/m <sup>3</sup>
$\sigma$	=	fragmentation correction coefficient
$\sigma_{FIT}$	=	standard deviation of the fit equation
Subscripts:		
crit	=	critical (i.e., causing tether cut-off)
h	=	hole
п	=	normal (to the tether surface)
р	=	projectile
t	=	target
thr	=	threshold
Acronyms:		
AHM	=	Adapted Hill Model
APSM	=	Adapted Piekutowski-Sorenson Model
BLE	=	Ballistic Limit Equation
HVI	=	Hypervelocity Impact
LGG	=	Light Gas Gun
PEEK	=	polyether ether ketone

### **Appendix A. Test Results**

Results of the experimental campaign [28], with ID identifying impact angles less than 80° (numbers) and at 90° (letters); edge impacts are indicated in grey. Uncertainties for the impact angle, the projectile speed, and the damage are also included. The last column on the left reports the value of the normal impact velocity  $v_n$ : tests 3, 8, 9, 14, and 21 show values less than 1 km/s.

				-				
Material	TEST ID	ID	α*,°	$d_p$ , mm	<i>t</i> <sub>0</sub> , mm	<i>v<sub>p</sub></i> **, km/s	A ***, mm	$v_n = v_p \cdot \cos(\alpha)$
Al-1100	8855	1	0	1.5	0.05	4.16	1.80	4.1600
Al-1100	8856	2	0	2.3	0.05	4.20	2.70	4.2000
Al-1100	8864	3	80	1.5	0.05	4.61	6.90	0.8005
Al-1100	8932	4	30	1.5	0.05	4.00	2.10	3.4641
Al-1100	8955	5	0	1.5	0.05	4.72	1.90	4.7200
Al-1100	8956	6	30	1.5	0.05	4.81	2.20	4.1656
Al-1100	8957	7	60	1.5	0.05	4.92	3.50	2.4600
Al-1100	8857	8	80	1.5	0.05	4.15	6.60	0.7206
Al-1100	8863	9	80	1.5	0.05	3.40	5.10	0.5904
Al-1100	8933	10	60	1.5	0.05	3.71	3.30	1.8550
Al-1100	8866	А	90	1.5	0.05	4.55	2.50	/
PEEK	8873	11	0	1.5	0.05	4.20	1.70	4.2000
PEEK	8874	12	0	2.3	0.05	4.08	2.40	4.0800
PEEK	8934	13	30	1.5	0.05	3.75	1.80	3.2476
PEEK	8939	14	80	1.5	0.05	3.89	7.00	0.6755
PEEK	8941	15	30	1.5	0.05	1.89	1.70	1.6368
PEEK	8942	16	30	1.5	0.05	1.98	1.70	1.7147
PEEK	8952	17	30	1.5	0.05	4.75	1.80	4.1136
PEEK	8953	18	60	1.5	0.05	4.44	2.90	2.2200
PEEK	8954	19	0	1.5	0.05	4.64	1.70	4.6400
PEEK	8935	20	60	1.5	0.05	3.63	3.10	1.8150
PEEK	8940	21	80	1.5	0.05	4.54	8.40	0.7884
PEEK	8869	А	90	1.5	0.05	3.52	3.00	/
PEEK	8871	В	90	1.5	0.05	4.48	2.30	/

Table A1. Hypervelocity impact experiments data; in grey, edge impacts.

\* uncertainty < 1  $^{\circ}$  \*\* uncertainty < 1 % \*\*\* uncertainty < 0.2 mm.

## **Appendix B. Simulation Parameters and Results**

Results of the simulation campaign [28] for impact angles below 80° (Table A2) and above 80° (Table A3); in grey, simulations that were interrupted close to the end, and for which a prediction of an approximate result was formulated.

Material	ID	$\alpha$ , °	$d_p$ , mm	t, mm	$v_p$ , km/s	A, mm	$v_n = v_p \cdot \cos \alpha$
PEEK	22	0	0.5	0.05	5	1.27	5
PEEK	23	0	0.5	0.05	12	1.27	12
PEEK	24	0	0.5	0.05	20	0.89	20
PEEK	25	0	1.50	0.05	5	1.82	5
PEEK	26	0	1.50	0.05	12	2.54	12
PEEK	27	0	1.50	0.05	20	2.16	20
PEEK	28	0	2.30	0.05	12	3.05	12

PEEK	29	0	2.30	0.05	20	3.56	20
PEEK	30	80	0.5	0.05	5	3.56	0.87
PEEK	31	80	0.5	0.05	12	3.68	2.08
PEEK	32	80	0.5	0.05	20	3.68	3.47
PEEK	33	80	1.50	0.05	5	6.68	0.87
PEEK	34	80	1.50	0.05	12	4.95	2.08
PEEK	35	80	1.50	0.05	20	4.06	3.47
PEEK	36	80	2.30	0.05	5	3.81	0.87
PEEK	37	80	2.30	0.05	12	5.46	2.08
Al-1100	38	0	0.5	0.05	5	1.27	5
Al-1100	39	0	0.5	0.05	12	1.14	12
Al-1100	40	0	0.5	0.05	20	1.02	20
Al-1100	41	0	1.50	0.05	5	2.17	5
Al-1100	42	0	1.50	0.05	12	2.03	12
Al-1100	43	0	1.50	0.05	20	2.42	20
Al-1100	44	0	2.30	0.05	20	3.68	20
Al-1100	45	80	0.5	0.05	12	3.94	2.08
Al-1100	46	80	0.5	0.05	20	4.46	3.47
Al-1100	47	80	1.50	0.05	5	5.08	0.87
Al-1100	48	80	1.50	0.05	12	8.00	2.08
Al-1100	49	80	1.50	0.05	20	6.98	3.47
Al-1100	50	80	2.30	0.05	5	7.11	0.87
Al-1100	51	80	2.30	0.05	12	3.94	2.08

Table A2. Cont.

**Table A3.** Numerical simulations at  $\alpha \sim 90^{\circ}$ ; interrupted simulations are highlighted.

Material	α, °	$d_p$ , mm	t, mm	w, mm	$v_p$ , km/s	A, mm
PEEK	88	0.5	0.05	25.4	5	11.05
PEEK	88	0.5	0.05	25.4	12	13.72
PEEK	88	0.5	0.05	25.4	20	14.72
PEEK	88	1.5	0.05	25.4	5	23.51
PEEK	88	1.5	0.05	25.4	12	23.51
PEEK	88	1.5	0.05	25.4	20	23.51
PEEK	88	2.3	0.05	25.4	5	21.99
PEEK	90	0.5	0.05	25.4	5	2.03
PEEK	90	0.5	0.05	25.4	12	1.27
PEEK	90	0.5	0.05	25.4	20	1.52
PEEK	90	1.5	0.05	25.4	5	4.70
PEEK	90	1.5	0.05	25.4	12	3.81
PEEK	90	1.5	0.05	25.4	20	3.94
PEEK	90	2.3	0.05	25.4	5	5.33
PEEK	90	2.3	0.05	25.4	12	4.19
PEEK	90	2.3	0.05	25.4	20	3.17
PEEK	90	9	0.05	25.4	20	25.40

Material	$\alpha$ , °	$d_p$ , mm	t, mm	<i>w</i> , mm	$v_p$ , km/s	A, mm
PEEK	90	9	0.05	25.4	5	25.40
PEEK	90	5	0.05	25.4	20	25.40
PEEK	90	5	0.05	25.4	5	25.40
PEEK	90	3	0.05	25.4	20	16.26
PEEK	90	3	0.05	25.4	5	11.18
PEEK	90	5	0.20	25.4	20	19.30
PEEK	90	5	0.20	25.4	5	21.34
PEEK	90	5	0.50	25.4	20	14.22
PEEK	90	5	0.50	25.4	5	14.22
PEEK	90	4	0.05	25.4	20	22.86
PEEK	90	4	0.05	25.4	5	25.40
PEEK	90	5	0.05	35.0	20	30.00
PEEK	90	5	0.05	35.0	5	33.00
PEEK	90	4	0.05	35.0	20	21.00
PEEK	90	4	0.05	35.0	5	25.29
PEEK	90	4	0.05	25.4	20	24.38
PEEK	90	4	0.05	25.4	5	23.00
Al-1100	88	0.5	0.05	25.4	5	0.00
Al-1100	88	0.5	0.05	25.4	12	0.00
Al-1100	88	0.5	0.05	25.4	20	1.91
Al-1100	88	1.5	0.05	25.4	5	23.38
Al-1100	88	1.5	0.05	25.4	20	23.51
Al-1100	88	2.3	0.05	25.4	5	21.60
Al-1100	90	0.5	0.05	25.4	5	1.78
Al-1100	90	0.5	0.05	25.4	12	1.40
Al-1100	90	0.5	0.05	25.4	20	2.41
Al-1100	90	1.5	0.05	25.4	5	3.56
Al-1100	90	1.5	0.05	25.4	12	3.56
Al-1100	90	1.5	0.05	25.4	20	3.56
Al-1100	90	2.3	0.05	25.4	20	1.14
Al-1100	90	15	0.05	25.4	20	25.40
Al-1100	90	15	0.05	25.4	5	25.40
Al-1100	90	10	0.05	25.4	20	25.40
Al-1100	90	10	0.05	25.4	5	25.40
Al-1100	90	9	0.05	25.4	20	15.24
Al-1100	90	9	0.05	25.4	20	15.24
Al-1100	90	9	0.05	25.4	5	25.40
Al-1100	90	6	0.05	25.4	20	24.38
Al-1100	90	6	0.05	25.4	5	25.40
Al-1100	90	3	0.05	25.4	20	16.26
Al-1100	90	3	0.05	25.4	5	12.19

Table A3. Cont.

Material	α, °	$d_p$ , mm	t, mm	<i>w,</i> mm	$v_p$ , km/s	A, mm
Al-1100	90	9	0.20	25.4	20	25.40
Al-1100	90	9	0.20	25.4	5	17.27
Al-1100	90	9	0.50	25.4	20	15.24
Al-1100	90	9	0.50	25.4	5	15.24
Al-1100	90	6	0.05	35.0	20	24.00
Al-1100	90	6	0.05	35.0	5	24.50

Table A3. Cont.

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