



H^2 -REGULARITY ON CONVEX DOMAINS FOR ROBIN EIGENFUNCTIONS WITH PARAMETER OF ARBITRARY SIGN

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Abstract

We prove that the Robin eigenfunctions on convex domains of \mathbb{R}^n are H^2 -regular regardless of the sign of the parameter involved in the boundary conditions. The proof is an adaptation of a classical argument used in the case of positive parameters combined with a Rellich-Pohozaev identity.

Keywords Robin eigenfunctions · Convex domain · H^2 -regularity

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Introduction

Let Ω be a bounded domain of \mathbb{R}^n , $n \geq 2$ (i.e., a bounded connected open set) with Lipschitz boundary, and $\beta \in \mathbb{R}$. In this paper, we consider the following eigenvalue problem:

$$\begin{cases} -\Delta u = \lambda u, & \text{in } \Omega, \\ \partial_\nu u + \beta u = 0, & \text{on } \partial\Omega. \end{cases} \quad (1)$$

Here, ν denotes the unit outer normal to $\partial\Omega$, and $\partial_\nu u$ is the normal derivative of u . Problem 1 is known as the *Robin problem* with parameter β . For $\beta = 0$, we have the Neumann eigenvalue problem, while for $\beta \rightarrow +\infty$, we recover the Dirichlet eigenvalue problem. In the literature, β is usually assumed to be positive, but in this paper, we do not impose any restriction on its sign. If the domain is not regular enough, Problem 1 has to be understood in the weak sense as follows:

$$\int_{\Omega} \nabla u \cdot \nabla \phi + \beta \int_{\partial\Omega} u \phi = \lambda \int_{\Omega} u \phi, \quad \forall \phi \in H^1(\Omega), \quad (2)$$

where the unknown u belongs to the Sobolev space $H^1(\Omega)$. By $H^m(\Omega)$, we denote the usual Sobolev space of functions in $L^2(\Omega)$ with weak derivatives up to order m in $L^2(\Omega)$.

In this paper, we prove the following.

Theorem 1 *Let Ω be a bounded convex domain in \mathbb{R}^n and $u \in H^1(\Omega)$ be a solution of Eq. 2. Then, $u \in H^2(\Omega)$.*

Theorem 1 is well known for $\beta \geq 0$ and $\beta = +\infty$, and the proof can be found, e.g., in the classical book by Grisvard [7, Theorem 3.2.3.1]. The proof in [7, §3] is based on the approximation of Ω by means of a sequence of smooth convex domains

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where the H^2 -regularity is known by classical regularity theory, and on uniform estimates of the H^2 -norms of the eigenfunctions on the approximating domains.

The condition $\beta \geq 0$ is used in a substantial way in [7, Theorem 3.2.3.1], and relaxing it is not straightforward. The same obstruction appears in the analysis of the Steklov problem and has been recently removed in [9]. In this paper, we adapt the method of [9] to the Robin problem with $\beta < 0$. Although our contribution seems to be new for $\beta < 0$, in this paper, we do not impose any restriction on the sign of β for the sake of completeness. As in [9], our proof is based on Reilly’s formula combined with the Rellich-Pohozaev identity. Moreover, in order to pass to the limit in the approximation procedure, we need a spectral stability result for the Robin problem. Again, the spectral stability is well known for $\beta \geq 0$ (see, e.g., [3]), and here, we also provide a proof for $\beta < 0$ in the case under consideration (see Theorem 9).

This paper is organized as follows. The “Preliminaries and notation” section is devoted to preliminaries and notation. In the “ H^2 -estimates on smooth convex domains” section, we prove the H^2 -estimates on smooth convex domains. In the “Spectral stability and proof of Theorem 1” section, we prove Theorem 9 concerning the spectral stability of the Robin problem and Theorem 1.

Preliminaries and notation

It is well known that Problem 2 can be considered an eigenvalue problem for a semi-bounded operator T with compact resolvent. In fact, Problem 2 is equivalent to

$$\int_{\Omega} \nabla u \cdot \nabla \phi + \beta \int_{\partial\Omega} u\phi + C \int_{\Omega} u\phi = \Lambda \int_{\Omega} u\phi, \quad \forall \phi \in H^1(\Omega), \tag{3}$$

where C is any real number and $\Lambda = \lambda + C$. By Corollary 4, it follows that there exists a positive constant C such that the quadratic form at the left-hand side of Eq. 3 is coercive in $H^1(\Omega)$. Thus, by standard spectral theory, there exists a self-adjoint operator T such that the quadratic form associated with $T + CI$ is precisely the one at the left-hand side of Eq. 3. Moreover, since Ω is bounded and convex, hence Lipschitz, the embedding $H^1(\Omega) \subset L^2(\Omega)$ is compact. Hence, $T + CI$ has a compact resolvent, its spectrum consists of a divergent sequence of positive eigenvalues of finite multiplicity, and the corresponding eigenfunctions can be chosen to form an orthonormal basis of $L^2(\Omega)$. In particular, it follows that the eigenvalues of T form a sequence of the type

$$-C < \lambda_1 < \lambda_2 \leq \dots \leq \lambda_j \leq \dots \nearrow +\infty. \tag{4}$$

We denote by $\{u_j\}_{j=1}^{\infty}$ a corresponding orthonormal basis of $L^2(\Omega)$ of eigenfunctions. Note that if $\beta > 0$, all eigenvalues are positive, while if $\beta < 0$, only a finite number of eigenvalues can be negative.

It is also standard to see that the eigenvalues can be represented by means of the Min-Max principle as follows:

$$\lambda_j = \min_{\substack{U \subset H^1(\Omega) \\ \dim U = j}} \max_{0 \neq u \in U} \frac{\int_{\Omega} |\nabla u|^2 + \beta \int_{\partial\Omega} u^2}{\int_{\Omega} u^2}. \tag{5}$$

As mentioned in the introduction, one of the main arguments in the proof of the H^2 -regularity of the Robin eigenfunctions is the approximation of a convex domain by smooth convex domains belonging to a uniform class. Namely, it will be required that the approximating domains can be locally described near the boundaries as the subgraphs of smooth functions with uniformly bounded gradients. It turns out that those domains belong to the same Lipschitz class. We find it convenient to recall the following definition from [2] involving the notion of atlas (see also [1]). Given a set $V \subset \mathbb{R}^n$ and a number $\delta > 0$, we write

$$V_{\delta} := \{x \in V : d(x, \partial V) > \delta\}, \tag{6}$$

where, for $x \in \mathbb{R}^n$ and $A \subset \mathbb{R}^n$, $d(x, A) := \inf_{a \in A} |x - a|$.

Definition 2 Let $\delta > 0, s, s' \in \mathbb{N}$ with $s' < s$. Let $\{V_j\}_{j=1}^s$ be a family of open cuboids (i.e., rotations of rectangle parallelepipeds in \mathbb{R}^n) and $\{r_j\}_{j=1}^s$ be a family of rotations in \mathbb{R}^n . We say that $\mathcal{A} = (\delta, s, s', \{V_j\}_{j=1}^s, \{r_j\}_{j=1}^s)$ is an atlas in \mathbb{R}^n with parameters $\delta, s, s', \{V_j\}_{j=1}^s, \{r_j\}_{j=1}^s$ briefly an atlas in \mathbb{R}^n . We say that a bounded domain $\Omega \subset \mathbb{R}^n$ is of class $C_M^{0,1}(\mathcal{A})$ if

- (i) $\Omega \subset \cup_{j=1}^s (V_j)_{\delta}$ and $(V_j)_{\delta} \cap \Omega \neq \emptyset$ where $(V_j)_{\delta}$ is meant in the sense given in Eq. 6;
- (ii) $V_j \cap \partial\Omega \neq \emptyset$ for $j = 1, \dots, s'$ and $V_j \cap \partial\Omega = \emptyset$ for $s' + 1 \leq j \leq s$;
- (iii) For $j = 1, \dots, s$, we have

$$\begin{aligned} r_j(V_j) &= \{x \in \mathbb{R}^n : a_{ij} < x_i < b_{ij}, i = 1, \dots, n\}, \quad j = 1, \dots, s; \\ r_j(V_j \cap \Omega) &= \{x = (x', x_n) \in \mathbb{R}^n : x' \in W_j, a_{nj} < x_n < g_j(x')\}, \quad j = 1, \dots, s' \end{aligned}$$

where $x' = (x_1, \dots, x_{n-1})$, $W_j = \{x' \in \mathbb{R}^{n-1} : a_{ij} < x_i < b_{ij}, i = 1, \dots, n-1\}$ and the functions $g_j \in C^{0,1}(\overline{W_j})$ for any $j \in 1, \dots, s'$ with $\|\nabla g_j\|_\infty \leq M$. Moreover, for $j = 1, \dots, s'$, we assume that $a_{nj} + \delta \leq g_j(x') \leq b_{nj} - \delta$, for all $x' \in \overline{W_j}$.

We say that a bounded domain $\Omega \subset \mathbb{R}^n$ is of class $C^{0,1}(\mathcal{A})$ if Ω is of class $C_M^{0,1}(\mathcal{A})$ for some $M > 0$.

Finally, we say that Ω is of class $C^{0,1}$ if it is of class $C_M^{0,1}(\mathcal{A})$ for some atlas \mathcal{A} and some $M > 0$.

We also need the following well-known technical lemma, which can be found, for example, in [7, Theorem 1.5.1.10]. For completeness, we include a proof to clarify how the constants depend on the geometry of the domain in our setting.

Lemma 3 *Let Ω be a bounded domain of class $C_M^{0,1}(\mathcal{A})$. For any $\varepsilon > 0$, there exists a positive constant $C(\varepsilon)$ depending only on $\varepsilon, \mathcal{A}, M$ such that*

$$\int_{\partial\Omega} u^2 \leq \varepsilon \int_{\Omega} |\nabla u|^2 + C(\varepsilon) \int_{\Omega} u^2, \tag{7}$$

for all $u \in H^1(\Omega)$.

Proof The proof is an adaptation of the classical proof of the trace theorem. We sketch the main steps. Following, e.g., [5, Theorem 1, §5.5], we begin by assuming that u is a smooth function and that the boundary is flat in a neighborhood of a point $x_0 \in \partial\Omega$. Namely, we assume that $\partial\Omega \cap B(x_0, r) = \{x = (x_1, \dots, x_n) \in B(x_0, r) : x_n = 0\}$. Next, we consider a non-negative smooth function ζ with compact support in $B(x_0, r)$ such that $\zeta \equiv 1$ in $B(x_0, r/2)$. Then, by the divergence theorem and by Cauchy's inequality, we get

$$\begin{aligned} \int_{\partial\Omega \cap B(x_0, r/2)} u^2 &\leq \int_{\partial\Omega \cap B(x_0, r)} \zeta u^2 = - \int_{\Omega \cap B(x_0, r)} \partial_{x_n}(\zeta u^2) \\ &= - \int_{\Omega \cap B(x_0, r)} u^2 \partial_{x_n} \zeta - 2 \int_{\Omega \cap B(x_0, r)} \zeta u \partial_{x_n} u \\ &\leq \|\partial_{x_n} \zeta\|_\infty \int_{\Omega \cap B(x_0, r)} u^2 + \varepsilon \|\zeta\|_\infty \int_{\Omega \cap B(x_0, r)} |\partial_{x_n} u|^2 + \frac{\|\zeta\|_\infty}{\varepsilon} \int_{\Omega \cap B(x_0, r)} u^2 \\ &\leq \varepsilon \|\zeta\|_\infty \int_{\Omega \cap B(x_0, r)} |\partial_{x_n} u|^2 + \left(\|\partial_{x_n} \zeta\|_\infty + \frac{\|\zeta\|_\infty}{\varepsilon} \right) \int_{\Omega \cap B(x_0, r)} u^2. \end{aligned} \tag{8}$$

In the general case, we flatten the boundary near x_0 by means of a bi-Lipschitz transformation ϕ with $\|\nabla\phi\|_\infty, \|\nabla\phi^{-1}\|_\infty \leq L$ where L depends only on M . By changing variables in integrals and rescaling ε , we obtain

$$\int_{\partial\Omega \cap B(x_0, r/2)} u^2 \leq \varepsilon \int_{\Omega \cap B(x_0, r)} |\nabla u|^2 + C(\varepsilon) \int_{\Omega \cap B(x_0, r)} u^2. \tag{9}$$

The proof can be completed by covering the boundary of Ω with a finite number (depending only on \mathcal{A}) of balls. □

By Lemma 3, we immediately deduce the following.

Corollary 4 *Under the same assumptions of Lemma 3, we have that for any $\beta \in \mathbb{R}$, there exists a non-negative constant C such that the quadratic form*

$$\int_{\Omega} |\nabla u|^2 + \beta \int_{\partial\Omega} u^2 + C \int_{\Omega} u^2$$

is coercive in $H^1(\Omega)$. In particular, if $\beta \geq 0$, one can choose any positive C , while if $\beta < 0$, we have for any $\varepsilon \in (0, -1/\beta)$ that the following inequality holds:

$$\int_{\Omega} |\nabla u|^2 + \beta \int_{\partial\Omega} u^2 - 2\beta C(\varepsilon) \int_{\Omega} u^2 \geq \min\{1 + \beta\varepsilon, -\beta C(\varepsilon)\} \int_{\Omega} (|\nabla u|^2 + u^2) \tag{10}$$

for all $u \in H^1(\Omega)$.

H^2 -estimates on smooth convex domains

In this section, we prove H^2 -estimates of L^2 -normalized Robin eigenfunctions on smooth convex domains Ω . It turns out that these estimates depend only on β (the Robin parameter), λ (the eigenvalue), the dimension, the diameter, the inradius of the

domain, and on the L^2 norm of the boundary traces. We recall that the diameter D and the inradius ρ of Ω are defined by

$$D = \sup_{x, y \in \Omega} |x - y|, \quad \rho = \sup_{x \in \Omega} \inf_{y \in \partial\Omega} |x - y|.$$

In order to prove our estimates, we need the Rellich-Pohozaev identity [10, 13] and Reilly’s formula [12]. The version of the Rellich-Pohozaev identity used in this paper is an adaptation to the Robin case of the identity proved in [11, Lemma 3.1].

Theorem 5 (Rellich-Pohozaev identity) *Let Ω be a bounded smooth domain in \mathbb{R}^n , and let $u \in H^2(\Omega)$ be such that $-\Delta u = \lambda u$ in $L^2(\Omega)$. Then,*

$$\frac{\lambda}{2} \int_{\partial\Omega} u^2 x \cdot \nu - \frac{\lambda n}{2} \int_{\Omega} u^2 + \frac{1}{2} \int_{\partial\Omega} (\partial_\nu u)^2 x \cdot \nu - \frac{1}{2} \int_{\partial\Omega} |\nabla_{\partial\Omega} u|^2 x \cdot \nu + \int_{\partial\Omega} \partial_\nu u x \cdot \nabla_{\partial\Omega} u + \frac{n-2}{2} \int_{\Omega} |\nabla u|^2 = 0, \quad (11)$$

where x denotes the position vector and $\nabla_{\partial\Omega}$ denotes the tangential component of the gradient.

Proof From [11, Lemma 3.1], we deduce that

$$\int_{\Omega} \Delta u x \cdot \nabla u = \frac{1}{2} \int_{\partial\Omega} (\partial_\nu u)^2 x \cdot \nu - \frac{1}{2} \int_{\partial\Omega} |\nabla_{\partial\Omega} u|^2 x \cdot \nu + \int_{\partial\Omega} \partial_\nu u x \cdot \nabla_{\partial\Omega} u + \frac{n-2}{2} \int_{\Omega} |\nabla u|^2. \quad (12)$$

On the other hand,

$$\int_{\Omega} u x \cdot \nabla u = \int_{\partial\Omega} u^2 x \cdot \nu - \int_{\Omega} u \operatorname{div}(ux) = \int_{\partial\Omega} u^2 x \cdot \nu - n \int_{\Omega} u^2 - \int_{\Omega} u x \cdot \nabla u \quad (13)$$

from which we get

$$\int_{\Omega} u x \cdot \nabla u = \frac{1}{2} \int_{\partial\Omega} u^2 x \cdot \nu - \frac{n}{2} \int_{\Omega} u^2. \quad (14)$$

The proof is concluded by using the equality $\int_{\Omega} (\Delta u + \lambda u) x \cdot \nabla u = 0$ and Eqs. 12 and 14. □

In what follows, by D^2u , we denote Hessian matrix of a function u and $|D^2u|^2 = \sum_{i,j=1}^n (\partial_{ij}^2 u)^2$.

Theorem 6 (Reilly’s formula) *Let Ω be a bounded smooth domain in \mathbb{R}^n , and let $u \in H^2(\Omega)$. Then,*

$$\int_{\Omega} |D^2u|^2 = \int_{\Omega} (\Delta u)^2 - \int_{\partial\Omega} [(n-1)\mathcal{H}(\partial_\nu u)^2 + 2\Delta_{\partial\Omega} u \partial_\nu u + II(\nabla_{\partial\Omega} u, \nabla_{\partial\Omega} u)], \quad (15)$$

where \mathcal{H} is the mean curvature of the boundary, II is the second fundamental form of the boundary, and $\Delta_{\partial\Omega}$ is the boundary Laplacian.

We are now ready to prove the following.

Lemma 7 *Let Ω be a bounded smooth convex domain in \mathbb{R}^n with diameter D and inradius ρ . Let u be an eigenfunction of Eq. 2 corresponding to the eigenvalue λ , normalized by $\int_{\Omega} u^2 = 1$. Then,*

$$\int_{\Omega} |D^2u|^2 \leq \lambda^2 - 2 \min\{\beta, 0\} C \left(D, \rho, \beta, \int_{\partial\Omega} u^2 \right), \quad (16)$$

where

$$C(D, \rho, \beta, t) := \left(D|\beta|t^{1/2} + \sqrt{(D^2\beta^2 - (\beta(n-2) - |\lambda + \beta^2|D)\rho)t - 2\lambda\rho} \right)^2 \rho^{-2}. \quad (17)$$

In particular, if $\beta \geq 0$, then

$$\int_{\Omega} |D^2u|^2 \leq \lambda^2, \quad (18)$$

while if $\beta < 0$, then

$$\int_{\Omega} |D^2u|^2 \leq \lambda^2 - 2\beta C \left(D, \rho, \beta, \frac{\varepsilon\lambda + C(\varepsilon)}{1 + \varepsilon\beta} \right), \quad (19)$$

for any $\varepsilon \in (0, -1/\beta)$, where $C(\varepsilon)$ is as in Lemma 3.

Proof Since Ω is smooth, by classical elliptic regularity, we have that $u \in H^2(\Omega)$ (see, e.g., [7, Chapter 2]). Following [9], we first estimate the L^2 -norm on $\partial\Omega$ of the tangential component of the gradient of u by a constant depending only on $n, \lambda, \beta, D, \rho$ and the L^2 -norm on $\partial\Omega$ of u .

Up to a translation, we may assume that $0 \in \Omega$ and that B_ρ is a ball of radius ρ centered at 0 contained in Ω . We observe that $\int_\Omega |\nabla u|^2 = \lambda - \beta \int_{\partial\Omega} u^2$ and that $\partial_\nu u = -\beta u$ on $\partial\Omega$ in the sense of traces, which are well defined in $L^2(\partial\Omega)$ since $u \in H^2(\Omega)$. After simplifications, we get from Eq. 11

$$2\lambda + \int_{\partial\Omega} |\nabla_{\partial\Omega} u|^2 x \cdot \nu + 2\beta \int_{\partial\Omega} u \nabla_{\partial\Omega} u \cdot x - (\lambda + \beta^2) \int_{\partial\Omega} u^2 x \cdot \nu + \beta(n-2) \int_{\partial\Omega} u^2 = 0.$$

Now, $|x| \leq D$ for all $x \in \Omega$ and $\rho \leq x \cdot \nu \leq D$ for all $x \in \partial\Omega$. Note that the inequality $x \cdot \nu \geq \rho$ follows from the convexity of Ω (see [9, Lemma 5]). Hence, we have

$$\frac{2\lambda}{\rho} + \int_{\partial\Omega} |\nabla_{\partial\Omega} u|^2 - \frac{2|\beta|D}{\rho} \left(\int_{\partial\Omega} |\nabla_{\partial\Omega} u|^2 \right)^{1/2} \left(\int_{\partial\Omega} u^2 \right)^{1/2} - \frac{|\lambda + \beta^2|D}{\rho} \int_{\partial\Omega} u^2 + \frac{\beta(n-2)}{\rho} \int_{\partial\Omega} u^2 \leq 0,$$

which reads

$$\frac{2\lambda}{\rho} + \int_{\partial\Omega} |\nabla_{\partial\Omega} u|^2 - \frac{2|\beta|D}{\rho} \left(\int_{\partial\Omega} |\nabla_{\partial\Omega} u|^2 \right)^{1/2} \left(\int_{\partial\Omega} u^2 \right)^{1/2} + \frac{\beta(n-2) - |\lambda + \beta^2|D}{\rho} \int_{\partial\Omega} u^2 \leq 0.$$

This is a second order equation in $(\int_{\partial\Omega} |\nabla_{\partial\Omega} u|^2)^{1/2}$ which implies the upper bound

$$\int_{\partial\Omega} |\nabla_{\partial\Omega} u|^2 \leq C \left(D, \rho, \lambda, \int_{\partial\Omega} u^2 \right). \tag{20}$$

Note that $C(D, \rho, \lambda, \int_{\partial\Omega} u^2)$ is well defined because the discriminant of the second-order equation under consideration must be non-negative.

Now, we use this estimate to bound the L^2 -norm of the Hessian of u . To do so, we first observe that the mean curvature \mathcal{H} is non-negative on $\partial\Omega$ and that II is a non-negative quadratic form on the tangent spaces to $\partial\Omega$ by the convexity of Ω . Then, by Reilly's formula 15, we get

$$\begin{aligned} \int_\Omega |D^2 u|^2 &= \lambda^2 - \int_{\partial\Omega} [\beta^2(n-1)\mathcal{H}u^2 - 2\beta\Delta_{\partial\Omega}uu + II(\nabla_{\partial\Omega}u, \nabla_{\partial\Omega}u)] \\ &\leq \lambda^2 + 2\beta \int_{\partial\Omega} \Delta_{\partial\Omega}uu = \lambda^2 - 2\beta \int_{\partial\Omega} |\nabla_{\partial\Omega}u|^2. \end{aligned} \tag{21}$$

By combining Eqs. 20 and 21, we deduce the validity of Eq. 16. Inequality 19 follows from Eqs. 7 and 16 and the equality $\int_\Omega |\nabla u|^2 = \lambda - \beta \int_{\partial\Omega} u^2$. \square

Spectral stability and proof of Theorem 1

We begin by recalling the following stability result from [4] and [8, §2]. By $d^{\mathcal{H}}(\Omega_1, \Omega_2)$, we denote the Hausdorff distance between two open sets Ω_1, Ω_2 , defined by

$$d^{\mathcal{H}}(\Omega_1, \Omega_2) := \max\left\{ \sup_{x \in \Omega_1} d(x, \Omega_2), \sup_{y \in \Omega_2} d(y, \Omega_1) \right\}.$$

Lemma 8 *Let Ω be a bounded convex domain in \mathbb{R}^n , and let $\{\Omega_k\}_{k=1}^\infty$ be a sequence of smooth convex domains such that $\Omega \subset \Omega_k$, $\Omega_{k+1} \subset \Omega_k$ for all $k \in \mathbb{N}$, and $\lim_{k \rightarrow \infty} d^{\mathcal{H}}(\Omega, \Omega_k) = 0$. Then, the inradius and the diameter of Ω_k converge to the inradius and the diameter of Ω , respectively, as $k \rightarrow \infty$. Moreover, for any $u_k \in H^1(\mathbb{R}^n)$ converging weakly in $H^1(\mathbb{R}^n)$ to $u \in H^1(\mathbb{R}^n)$, we have*

$$\lim_{k \rightarrow \infty} \int_{\partial\Omega_k} u_k^2 = \int_{\partial\Omega} u^2.$$

Next, we prove the following spectral stability result.

Theorem 9 *Let Ω be a bounded convex domain in \mathbb{R}^n , and let $\Omega_k, k \in \mathbb{N}$, be a sequence of bounded smooth convex domains, with $\Omega \subset \Omega_{k+1} \subset \Omega_k$ for all $k \in \mathbb{N}$, such that $\lim_{k \rightarrow +\infty} d^{\mathcal{H}}(\Omega, \Omega_k) = 0$. Let $\lambda_j(k), \lambda_j$ denote the Robin eigenvalues of Ω_k, Ω , respectively. Then,*

$$\lim_{k \rightarrow \infty} \lambda_j(k) = \lambda_j, \tag{22}$$

for all $j \in \mathbb{N}$. Moreover, if $\{u_j(k)\}_{j=1}^\infty$ is an orthonormal basis of $L^2(\Omega_k)$ of Robin eigenfunctions associated with $\lambda_j(k)$, then there exists an orthonormal basis $\{u_j\}_{j=1}^\infty$ of $L^2(\Omega)$ of Robin eigenfunctions associated with λ_j such that, possibly passing to a subsequence with respect to k , we have

$$\lim_{k \rightarrow \infty} \|u_j(k) - u_j\|_{H^1(\Omega)} = 0. \quad (23)$$

Proof The proof is divided into three steps.

Step 1. We fix $j \in \mathbb{N}$, and we prove that $\lambda_j(k) \rightarrow \lambda_j$ as $k \rightarrow \infty$. Let $v_i, i = 1, \dots, j$, be a $L^2(\Omega)$ orthonormal family of Robin eigenfunctions in Ω , with associated eigenvalues λ_i . Let $\tilde{v}_i \in H^1(\mathbb{R}^n)$ be some extension of v_i to \mathbb{R}^n , and let $\tilde{V}_j = \{\sum_{i=1}^j a_i \tilde{v}_i : \sum_{i=1}^j a_i^2 = 1, a_i \in \mathbb{R}\}$. From Lemma 8, we deduce that there exists $\varepsilon(j, k) > 0$ such that

$$1 - \varepsilon_1(j, k) \leq \frac{\int_{\partial\Omega_k} \tilde{v}^2}{\int_{\partial\Omega} v^2} \leq 1 + \varepsilon_1(j, k)$$

for all $\tilde{v} \in \tilde{V}_j$, where $\varepsilon_1(j, k) \rightarrow 0$ as $k \rightarrow \infty$. Here, by v , we denote the restriction of $\tilde{v} \in \tilde{V}_j$ to Ω . We have

$$\begin{aligned} \lambda_j(k) &\leq \max_{\tilde{v} \in \tilde{V}_j} \frac{\int_{\Omega_k} |\nabla \tilde{v}|^2 + \beta \int_{\partial\Omega_k} \tilde{v}^2}{\int_{\Omega_k} \tilde{v}^2} \leq \max_{\tilde{v} \in \tilde{V}_j} \frac{\int_{\Omega} |\nabla v|^2 + \beta(1 + \text{sign}(\beta)\varepsilon_1(j, k)) \int_{\partial\Omega} v^2 + \int_{\Omega_k \setminus \Omega} |\nabla \tilde{v}|^2}{\int_{\Omega} v^2} \\ &\leq \max_{\tilde{v} \in \tilde{V}_j} \frac{\int_{\Omega} |\nabla v|^2 + \beta \int_{\partial\Omega} v^2}{\int_{\Omega} v^2} + \max_{\tilde{v} \in \tilde{V}_j} \frac{\int_{\Omega_k \setminus \Omega} |\nabla \tilde{v}|^2 + \text{sign}(\beta)\varepsilon_1(j, k)\beta \int_{\partial\Omega} v^2}{\int_{\Omega} v^2} \\ &\leq \lambda_j + \max_{\tilde{v} \in \tilde{V}_j} \left(\int_{\Omega_k \setminus \Omega} |\nabla \tilde{v}|^2 + \text{sign}(\beta)\varepsilon_1(j, k)\beta \int_{\partial\Omega} v^2 \right) \leq \lambda_j + \varepsilon_2(j, k), \quad (24) \end{aligned}$$

where $\varepsilon_2(j, k) \rightarrow 0$ as $k \rightarrow \infty$. The last inequality in Eq. 24 follows from the absolute continuity of the Lebesgue integral combined with the fact that \tilde{V}_j is finite dimensional.

Now, let $\{u_i(k)\}_{i=1}^\infty$ be an orthonormal basis of $L^2(\Omega_k)$ of Robin eigenfunctions associated with $\lambda_i(k)$. We show that the restrictions of $\{u_i(k)\}_{i=1}^j$ to Ω are linearly independent for k large enough. It follows by [7, Lemma 3.2.3.2] that the domains Ω and Ω_k belong to the same atlas class $C_M^{0,1}(\mathcal{A})$ for all k sufficiently large. Hence, by inequality 24, by Corollary 4, and by the normalization of $u_i(k)$, it follows that the norm $\|u_i(k)\|_{H^1(\Omega_k)}$ is uniformly bounded with respect to k . We show that $\lim_{k \rightarrow \infty} \int_{\Omega_k \setminus \Omega} u_i(k) u_\ell(k) = 0$ for all $i, \ell = 1, \dots, j$. This implies that for k sufficiently large, $u_i(k)$ are linearly independent in $L^2(\Omega)$. Indeed, by the Hölder's inequality, the Sobolev Embedding Theorem, and the uniform bound on the $H^1(\Omega_k)$ norms of the eigenfunctions, we have

$$\begin{aligned} \left| \int_{\Omega_k \setminus \Omega} u_i(k) u_\ell(k) \right| &\leq \|u_i(k)\|_{L^2(\Omega_k \setminus \Omega)} \|u_\ell(k)\|_{L^2(\Omega_k \setminus \Omega)} \\ &\leq |\Omega_k \setminus \Omega|^{1-2/p} \|u_i(k)\|_{L^p(\Omega_k \setminus \Omega)} \|u_\ell(k)\|_{L^p(\Omega_k \setminus \Omega)} \leq C |\Omega_k \setminus \Omega|^{1-2/p} \quad (25) \end{aligned}$$

for some $p > 2$, where C is independent on k . From now on, we assume directly that the functions $u_i(k)$ are extended to the whole \mathbb{R}^n with norms in $H^1(\mathbb{R}^n)$ uniformly bounded, and that (possibly passing to a subsequence with respect to k) $u_i(k)$ is weakly convergent in $H^1(\mathbb{R}^n)$ as $k \rightarrow \infty$, and strongly in $L^2(\Omega)$. Let $V_j(k) = \{\sum_{i=1}^j a_i u_i(k) : \sum_{i=1}^j a_i^2 = 1, a_i \in \mathbb{R}\}$. We have

$$\begin{aligned} \lambda_j &\leq \max_{v \in V_j(k)} \frac{\int_{\Omega} |\nabla v|^2 + \beta \int_{\partial\Omega} v^2}{\int_{\Omega} v^2} \leq \max_{v \in V_j(k)} \frac{\int_{\Omega_k} |\nabla v|^2 + \beta(1 + \text{sign}(\beta)\varepsilon_3(j, k)) \int_{\partial\Omega_k} v^2}{\int_{\Omega} v^2} \\ &\leq \max_{v \in V_j(k)} \frac{\int_{\Omega_k} |\nabla v|^2 + \beta \int_{\partial\Omega_k} v^2}{\int_{\Omega_k} v^2} \frac{\int_{\Omega_k} v^2}{\int_{\Omega} v^2} + \varepsilon_3(j, k) |\beta| \max_{v \in V_j(k)} \frac{\int_{\partial\Omega_k} v^2}{\int_{\Omega} v^2} \\ &\leq \lambda_j(k) \max_{v \in V_j(k)} \frac{\int_{\Omega_k} v^2}{\int_{\Omega} v^2} + \varepsilon_3(j, k) |\beta| C \leq \lambda_j(k) (1 + \text{sign}(\lambda_j(k))\varepsilon_4(j, k)) + \varepsilon_3(j, k) |\beta| C \quad (26) \end{aligned}$$

with $\varepsilon_3(j, k), \varepsilon_4(j, k) \rightarrow 0$ as $k \rightarrow \infty$ for fixed j . In the second inequality, we have used

$$1 - \varepsilon_3(j, k) \leq \frac{\int_{\partial\Omega} v^2}{\int_{\partial\Omega_k} v^2} \leq 1 + \varepsilon_3(j, k)$$

for all $v \in V_j(k)$. In the fourth inequality, we have used, for the first summand, that

$$\frac{\int_{\Omega_k} |\nabla v|^2 + \beta \int_{\partial\Omega_k} v^2}{\int_{\Omega_k} v^2} \leq \lambda_j(k)$$

for all $v \in V_j(k)$; for the second summand, we have used that $\int_{\Omega} u_i(k)u_h(k) \rightarrow \delta_{ih}$ as $k \rightarrow \infty$ for all $i, h = 1, \dots, j$, and that $\int_{\partial\Omega_k} u_i(k)^2 = O(1)$ as $k \rightarrow \infty$ by Eq. 7 for all $i = 1, \dots, j$. In the fifth inequality, we have used

$$1 - \varepsilon_4(j, k) \leq \frac{\int_{\Omega_k} v^2}{\int_{\Omega} v^2} \leq 1 + \varepsilon_4(j, k).$$

Inequality 26 combined with Eq. 24 implies that $\lambda_j(k) \rightarrow \lambda_j$ for all j as $k \rightarrow \infty$.

Step 2. By Lemma 7 and the uniform bounds for the norms in $H^1(\Omega_k)$ of the eigenfunctions (see Step 1), we have that $\{u_j(k)\}_{k=1}^{\infty}$ is bounded in $H^2(\Omega)$. Up to extracting a subsequence, we find $u_j \in H^2(\Omega)$ such that $u_j(k) \rightarrow u_j$ in $H^1(\Omega)$. We now show that u_j is an eigenfunction with eigenvalue λ_j . Let Φ be a Lipschitz continuous function defined in \mathbb{R}^n . Then,

$$\int_{\Omega_k} \nabla u_j(k) \cdot \nabla \Phi + \beta \int_{\partial\Omega_k} u_j(k)\Phi = \lambda_j(k) \int_{\Omega_k} u_j(k)\Phi. \tag{27}$$

We consider the boundary integral in the left-hand side of Eq. 27, and we write

$$\int_{\partial\Omega_k} u_j(k)\Phi = \int_{\partial\Omega} u_j\Phi + \left(\int_{\partial\Omega_k} u_j(k)\Phi - \int_{\partial\Omega} u_j\Phi \right).$$

The second term in the right-hand side goes to zero as $k \rightarrow \infty$ thanks to Lemma 8. For the volume integral in left-hand side of Eq. 27, we have

$$\int_{\Omega_k} \nabla u_j(k) \cdot \nabla \Phi = \int_{\Omega} \nabla u_j \cdot \nabla \Phi + \int_{\Omega_k \setminus \Omega} \nabla u_j(k) \cdot \nabla \Phi + \left(\int_{\Omega} \nabla(u_j(k) - u_j) \cdot \nabla \Phi \right). \tag{28}$$

The second term in the right-hand side of Eq. 28 goes to zero as $k \rightarrow \infty$ because

$$\int_{\Omega_k \setminus \Omega} \nabla u_j(k) \cdot \nabla \Phi \leq \|\nabla u_j(k)\|_{L^2(\Omega_k \setminus \Omega)} \|\nabla \Phi\|_{L^2(\Omega_k \setminus \Omega)} \leq C \|\nabla \Phi\|_{L^2(\Omega_k \setminus \Omega)}$$

and because $\|\nabla \Phi\|_{L^2(\Omega_k \setminus \Omega)}$ goes to zero as before by the absolute continuity of the Lebesgue integral. The third term in Eq. 28 goes to zero since $u_j(k) \rightarrow u_j$ in $H^1(\Omega)$. In the same way, one can see that the volume integral in the right-hand side of Eq. 27 converges to $\int_{\Omega} u_j\Phi$ as $k \rightarrow \infty$. In conclusion,

$$\int_{\Omega} \nabla u_j \cdot \nabla \Phi + \beta \int_{\partial\Omega} u_j\Phi = \lambda_j \int_{\Omega} u_j\Phi, \tag{29}$$

and Eq. 23 holds. Since Eq. 29 holds for all Lipschitz function Φ defined in \mathbb{R}^n , by a density argument, we conclude that Eq. 29 holds for all $\Phi \in H^1(\Omega)$; hence, u_j is a Robin eigenfunction in Ω .

Step 3. We prove that $\{u_j\}_{j=1}^{\infty}$ is an orthonormal basis of $L^2(\Omega)$. This follows simply by passing to the limit in the equality $\int_{\Omega_k} u_i(k)u_j(k) = \delta_{ij}$ as $k \rightarrow \infty$ in order to get $\int_{\Omega} u_i u_j = \delta_{ij}$. In fact, writing

$$\int_{\Omega_k} u_i(k)u_j(k) = \int_{\Omega} u_i(k)u_j(k) + \int_{\Omega_k \setminus \Omega} u_i(k)u_j(k)$$

we have that the first integral in the right-hand side of the previous equality converges to $\int_{\Omega} u_i u_j$ while the second integral converges to zero by Eq. 25. □

We are ready to prove Theorem 1.

Proof of Theorem 1 By [7, Lemma 3.2.1.1], there exists a sequence of bounded smooth convex domains $\{\Omega_k\}_{k=1}^{\infty}$ such that $\Omega \subset \Omega_{k+1} \subset \Omega_k$ for all $k \in \mathbb{N}$, and such that $\lim_{k \rightarrow \infty} d^{\mathcal{H}}(\Omega_k, \Omega) = 0$. Let $\lambda_j(k)$ denote the Robin eigenvalues of Ω_k , and let $\{u_j(k)\}_{j=1}^{\infty}$ be an orthonormal basis of $L^2(\Omega_k)$ of corresponding eigenfunctions. By Theorem 9, $\lambda_j(k) \rightarrow \lambda_j$ as $k \rightarrow \infty$, where λ_j are the Robin eigenvalues on Ω , and there exists an orthonormal basis $\{u_j\}_{j=1}^{\infty}$ of $L^2(\Omega)$ of eigenfunctions associated with the λ_j 's such that Eq. 23 holds, possibly passing to a subsequence with respect to k .

Consider any domain ω with $\bar{\omega} \subset \Omega$. Now, we have $-\Delta(u_j(k) - u_j) = \lambda_j(k)u_j(k) - \lambda_j u_j$, and by Eq. 23, it follows that $\|\lambda_j(k)u_j(k) - \lambda_j u_j\|_{H^1(\Omega)} \rightarrow 0$ as $k \rightarrow \infty$. It follows by elliptic regularity (see, e.g., [6, Theorem 8.10]) that $\lim_{k \rightarrow \infty} \|u_j(k) - u_j\|_{H^2(\omega)} = 0$. In particular, by Eq. 18, if $\beta \geq 0$, we have

$$\int_{\omega} |D^2 u_j|^2 = \lim_{k \rightarrow \infty} \int_{\omega} |D^2 u_j(k)|^2 \leq \lim_{k \rightarrow \infty} \lambda_j(k)^2 = \lambda_j^2. \quad (30)$$

If $\beta < 0$, by Eq. 19 and by the continuity of $C(D, \rho, \beta, t)$ (see Eq. 17), we have that

$$\begin{aligned} \int_{\omega} |D^2 u_j|^2 &= \lim_{k \rightarrow \infty} \int_{\omega} |D^2 u_j(k)|^2 \leq \lim_{k \rightarrow \infty} \left(\lambda_j(k)^2 - 2\beta C \left(D(k), \rho(k), \beta, \frac{\varepsilon \lambda_j(k) + C(\varepsilon)}{1 + \varepsilon \beta} \right) \right) \\ &= \lambda_j^2 - 2\beta C \left(D, \rho, \beta, \frac{\varepsilon \lambda_j + C(\varepsilon)}{1 + \varepsilon \beta} \right), \end{aligned} \quad (31)$$

where ε is any fixed constant satisfying $\varepsilon \in (0, -1/\beta)$. Here, $D(k), \rho(k)$ are the diameter and inradius of Ω_k , while D, ρ are the diameter and inradius of Ω .

Consider now a sequence of domains $\omega_{\ell} \subset \Omega$ such that $\bar{\omega}_{\ell} \subset \Omega$, $\omega_{\ell} \subset \omega_{\ell+1}$, $\bigcup_{\ell=1}^{\infty} \omega_{\ell} = \Omega$. Then, by considering Eqs. 30 and 31 with ω replaced by ω_{ℓ} and passing to the limit as $\ell \rightarrow \infty$, we get that

$$\int_{\Omega} |D^2 u_j|^2 \leq \lambda_j, \quad \text{if } \beta \geq 0, \quad (32)$$

$$\int_{\Omega} |D^2 u_j|^2 \leq \lambda_j^2 - 2\beta C \left(D, \rho, \beta, \frac{\varepsilon \lambda_j + C(\varepsilon)}{1 + \varepsilon \beta} \right), \quad \text{if } \beta < 0, \quad (33)$$

hence $u_j \in H^2(\Omega)$. Since the functions $\{u_j\}_{j=1}^{\infty}$ form a complete system in $L^2(\Omega)$, all other eigenfunctions are linear combinations of a finite number of those eigenfunctions; hence, they belong to $H^2(\Omega)$. \square

Remark 10 We remark that formula Eq. 32 is the estimate found in [7, §3].

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Data availability No data are associated with this article.

Declarations

Conflict of interest The authors declare no competing interests.

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